

DuraForce™ HMV / HMR / HMF / HMA
Closed and Open Loop Hydraulic Motor

LIFCO
HYDRAULICS INC

LIFCOHYDRAULICS.COM
1-800-895-4326



EATON

Powering Business Worldwide

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The DuraForce Closed and Open Loop Hydraulic Motor

Design Characteristics

- High pressure axial piston motor in swash plate design for closed and open loop systems
- Optionally with purge valves for circuit and case flushing
- HP valves possible
- Through-shaft with bare shaft end or coupling flange
- Plug-in version optional
- Speed sensor optional

Typical Applications

- Excavator
- Ground Drive
- Drill Heads
- Trencher Drive
- Horizontal Drill Drive
- Oil and Gas Markets
- Offshore Marine
- Winch

Features

- Optimized start-up
- Low-speed characteristics
- SAE High pressure ports, radial or axial
- SAE mounting flange with ANSI or SAE spline shaft

Product Advantages

- Smooth low-speed operation
- High starting torque
- Lower emissions through speed reduction
- Compact design
- High power density
- High reliability
- Long service life
- Highly dynamic response characteristics
- Simplified drive line



Eaton

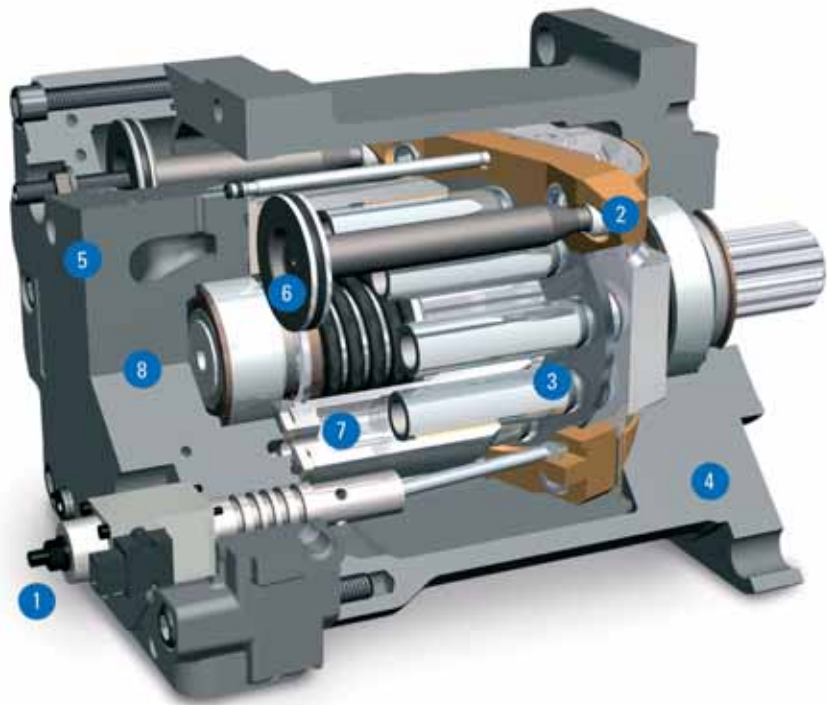
Open and Closed Loop Motor

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Product Characteristics

- 1. Control**
Optional swashing to 0 cm³/rev
- 2. Swash Plate**
Hydrostatic bearing
- 3. Piston-slipper Assembly**
21° swash angle
- 4. Housing**
Monoshell for high rigidity
- 5. Valve Plate Housing**
Highly integrated
- 6. Control Piston**
Integrated, hydraulically captured
- 7. Rotating Group**
Precise torque transmission even at low speeds
- 8. Optional Trough-Drive**
Available with two shaft ends for torque transmission

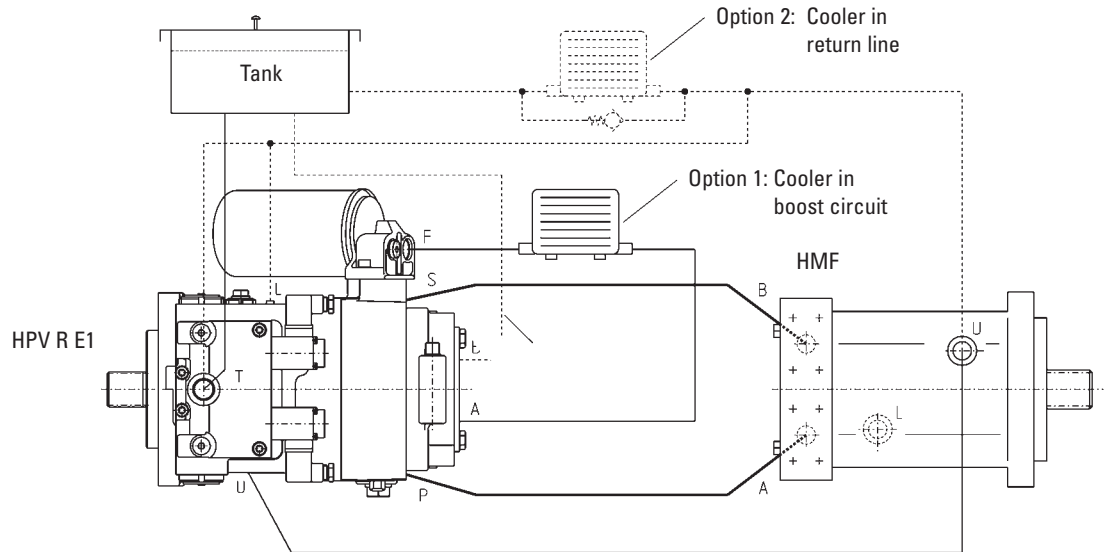


Product Range
Find the right products for your application.

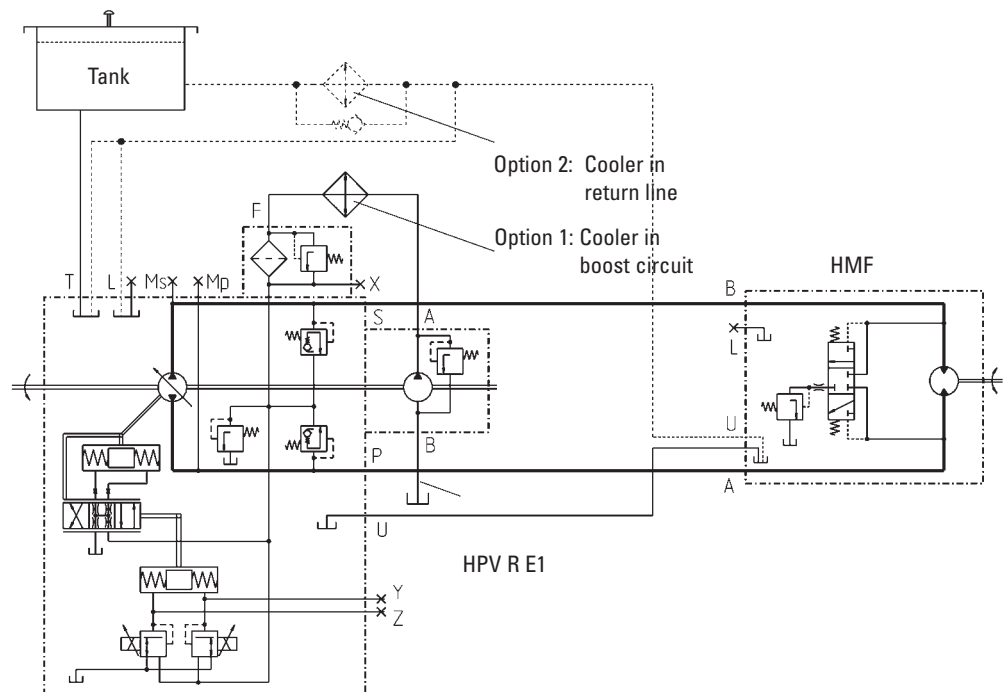
Product	Application	Product Name
Pump		
Self-regulating pump	Open loop operation	HPR
Variable pump	Closed loop operation	HPV
Motor		
Variable motor	Closed and open loop operation	HMV
Regulating motor	Closed and open loop operation	HMR
Fixed motor	Closed and open loop operation	HMF
	Open loop operation	HMF P
	Closed and open loop operation	HMA

Representation of the hydraulic components of a closed loop hydrostatic drive: Variable electrohydraulic controlled pump HPV R E1 and fixed displacement motor HMF plus filter, cooler and oil tank. The function diagram and the circuit diagram show two types of cooling.

Function Diagram



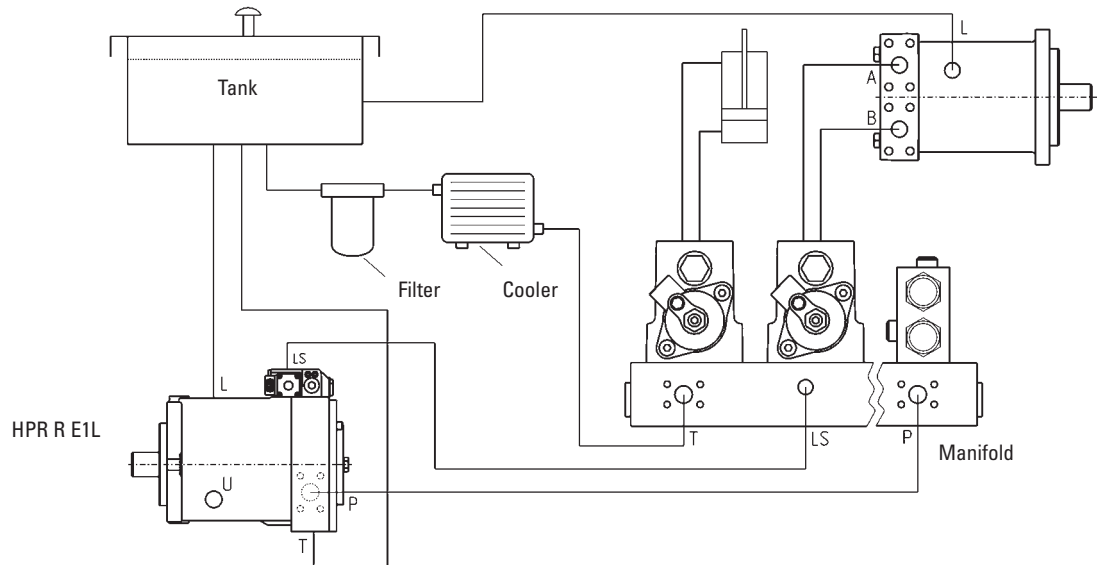
Circuit Diagram



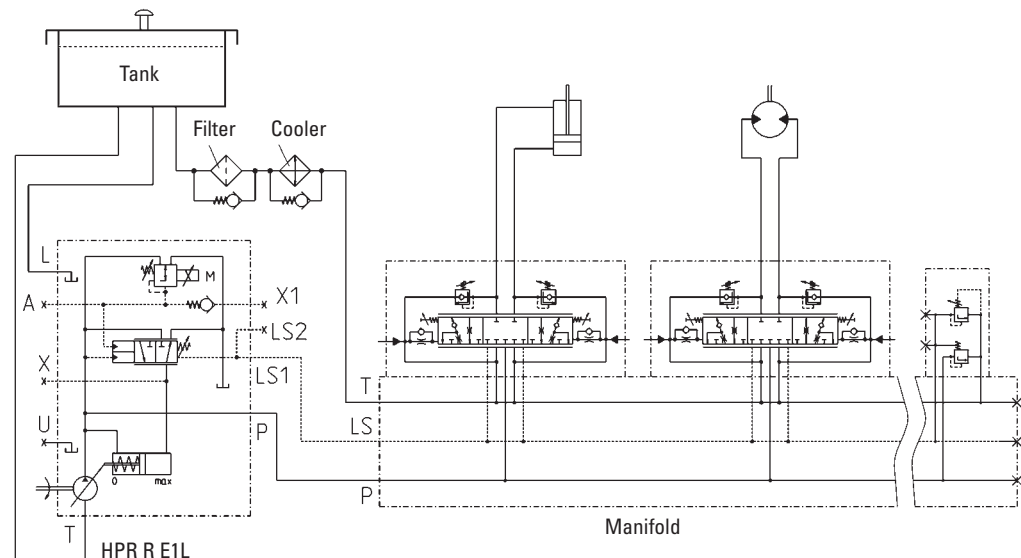
Representation of hydraulic components in an open loop circuit, based on the LSC system as an example: A HPR regulating pump with load sensing function for energy-saving flow on demand control and VW load sensing directional control valves for load independent and simultaneous movements of several consumers without mutual influencing. The system is complemented with proven Eaton products such as electronic controllers, swing drive and hydraulic motors.

The Open Loop

Function Diagram



Circuit Diagram



Further information about the LSC system is available in the HPR data sheet or directly from our sales engineers.

Specifications and Technical Data

Overview Displacements 28-105

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Specifications

Model			28	35	50/55	75	105
Rated Size Displacement HMF 50 (w/o directional control valve) HMV can be set to 0 cm ³ /rev displacement	Maximum V _{max}	cm ³ /rev	28.6	35.6	54.8	75.9	105.0
	Minimum V _{min} only for variable and regulating motors	cm ³ /rev	—	—	18.3	25.3	35.0
Speed	Max. continuous speed (100 % duty cycle) at maximum displacement	min ⁻¹	4500	4500	4100	3800	3500
	Max. speed (intermittent) at maximum displacement, higher speed on request	min ⁻¹	4800	4800	4400	4100	3800
	Max. continuous speed (100 % duty cycle) at min. displacement	min ⁻¹	—	—	4700	4400	4100
	Max. speed (intermittent) at minimum displacement, higher speed on request	min ⁻¹	—	—	5300	5000	4700
Pressure	Nominal pressure other values on request	bar			420		
	Peak pressure	bar			500		
	Continuous pressure (p)	bar			250		
	Permissible Housing pressure (Absolute)	bar			2.5		
Torque (Theoretical)	Continuous output torque at continuous pressure	Nm	114	142	199/218	302	418
	Max. output torque at maximum operating pressure	Nm	191	238	334/366	508	702
Power (Theoretical)	Continuous power at maximum continuous speed, maximum displacement and continuous pressure	kW	54	67	85/94	120	153
	Maximum Power at max. continuous speed, max. displacement and max. operating pressure	kW	90	112	143/157	202	257
Permissible Shaft Loads	Axial input /output force	N			2000		
	Radial	N			on request		
Perm. Housing Temp.	Perm. housing temperature with minimum perm. viscosity > 10 cSt	°C °F			90°C 194°F		
Weights	Fixed displacement motor with 2-hole mounting flange	kg	16	16	19	26	33
	Variable and regulating motor with 2- or 4-hole mounting flange	kg	—	—	28	32	42
	Max. moment of inertia	kgm ² x 10 ⁻²	0.25	0.25	0.49	0.79	1.44

Specifications and Technical Data

Overview Displacements 135-135D

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Specifications

Model			135	165	210	280	135D
Rated Size Displacement HMV can be set to 0 cm ³ /rev displacement	Maximum Vmax HMF 50 (w/o directional control valve) have 51.3 cm ³ /rev displacement, thus torque and power change accordingly	cm ³ /rev	135.6	165	210	280	270
	Minimum Vmin only for variable and regulating motors	cm ³ /rev	45.2	55.2	70	93	67
Speed	Max. continuous speed (100 % duty cycle) at maximum displacement	min ⁻¹	3200	3100	2700	2400	3200
	Max. speed (intermittent) at maximum displacement, higher speed on request	min ⁻¹	3500	3400	3000	2700	3500
	Max. continuous speed (100 % duty cycle) at minimum displacement	min ⁻¹	3700	3500	3200	2900	3700
	Max. speed (intermittent) at minimum displacement, higher speed on request	min ⁻¹	4000	3900	3500	3200	4000
Pressure	Nominal pressure other values in request	bar			420		
	Peak pressure	bar			500		
	Continuous pressure (Δp)	bar			250		
	Permissible housing pressure (absolute)	bar			2.5		
Torque (Theoretical)	Continuous output torque at continuous pressure	Nm	540	657	836	1115	1075
	Max. output torque at maximum operating pressure	Nm	907	1104	1404	1872	1803
Power (Theoretical)	Continuous power at maximum continuous speed, maximum displacement and continuous pressure	kW	181	213	236	280	360
	Maximum power at max. continuous speed, max. displacement and max. operating pressure	kW	304	358	397	470	605
Permissible Shaft Loads	Axial input / output force	N			2000		
	Radial	N			on request		
Perm. housing temperature	Perm. housing temperature with minimum perm. viscosity > 10 cSt	°C °F			90°C 194°F		
Weights	Fixed displacement motor with 2-hole mounting flange	kg	39	75	100	-	-
	Variable and regulating motor with 2- or 4-hole mounting flange	kg	56	76	101	146	149
	Max. moment of inertia	kgm ² x 10 ⁻²	2.15	3.06	4.68	9.36	2.15

Model Code

HMV

Variable Displacement Motors
(Open & Closed Loop Operation)

The following 31 digit coding system has been developed to identify preferred feature options for the Eaton Closed or Open Loop Hydraulic Motor. Use this code to specify a motor with the desired features. All 31-digits of the code must be present to release a new product number for ordering. Please contact your local customer service representative for leadtime questions.

HMV	055	A	C	M	1	0	A	0	0	0	0	0	000	000	000	00	0	A	A
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
21	22	23	24	25	26	27	28	29	30	31									

	55	75	105	135	165	210	280
1 2 3 Product							
HMV – Adjustable Fixed Displacement Motors	•	•	•	•	•	•	•
4 5 6 Displacement							
055 – 055 cc	•						
075 – 075 cc		•					
105 – 105 cc			•				
135 – 135 cc				•			
165 – 165 cc					•		
210 – 210 cc						•	
280 – 280 cc							•
7 Mounting Flange							
A – SAE J744 standard	•	•	•	•	•	•	•
P – Plug-in (*d)		•	•	•	•		
8 Output Shaft							
C – Splined ANSI B92.1 12/24 - 14 teeth (SAE J744 C)	•	•	•				
D – Splined ANSI B92.1 8/16 - 13 teeth (SAE J744 D&E)				•	•		
F – Splined ANSI B92.1 8/16 - 15 teeth (SAE J744 F)						•	•
K – Splined ANSI B92.1 16/32 - 21 teeth	•	•					
L – Splined ANSI B92.1 16/32 - 23 teeth			•				
M – Splined ANSI B92.1 16/32 - 27 teeth				•	•	•	
N – Splined ANSI B92.1 16/32 - 33 teeth							•
P – Shaft coupling flange size 4						•	•
9 Porting							
M – ISO 6149 metric	•	•	•	•	•	•	•
D – DIN 3852	•	•	•	•	•		
10 Port Orientation							
1 – Radial ports / without PTO	•	•	•	•	•	•	•
2 – Axial ports / without PTO			•	•	•		
3 – Radial ports / splined PTO shaft ANSI B92.1 16/32 - 19 teeth			•				
4 – Radial ports / splined PTO shaft ANSI B92.1 16/32 - 21 teeth				•			
5 – Radial ports / splined PTO shaft ANSI B92.1 16/32 - 22 teeth					•		
6 – Radial ports / splined PTO shaft ANSI B92.1 16/32 - 24 teeth						•	
7 – Radial ports / splined PTO shaft ANSI B92.1 16/32 - 27 teeth							•
8 – Radial ports / PTO shaft coupling flange size 4						•	•
9 – Radial ports / PTO speed sensor 35 impulses	•	•	•	•	•	•	•
11 Attachments to Service Ports							
0 – Without	•	•	•	•	•	•	•
1 – Crossover relief block 250 bar (*p)					•	•	•
2 – Crossover relief block 300 bar (*p)					•	•	•
3 – Crossover relief block 380 bar (*p)					•	•	•
4 – Crossover relief block 420 bar (*p)					•	•	•
12 Motor Control							
A – H1: hydraulic proportional / standard mounting	•	•	•	•	•	•	•
B – E1: electro-proportional / standard mounting	•	•	•	•	•	•	•
C – E2: electric two position / standard mounting	•	•	•	•	•	•	•

	55	75	105	135	165	210	280
D – E4: electro-proportional / Vmin = 0 / standard mounting	•	•	•	•	•	•	•
K – EH1P: hydraulic proportional / PCO		•	•	•	•		
L – H1-CA: hydraulic proportional / CA operation (*m)					•	•	
M – EH1P-CA: hydraulic proportional / PCO / CA operation			•	•	•	•	
13 Control Threshold Pressure							
0 – not applicable (E1; E2; E4; E6)	•	•	•	•	•	•	•
1 – 7,0 bar (H1; EH1P; EH1P-CA)	•	•	•	•	•	•	•
2 – 7,5 bar (H1; EH1P; H1-CA)	•	•	•	•	•	•	•
3 – 8,0 bar (H1; EH1P)	•	•	•	•	•	•	•
14 Control Solenoids							
0 – Not applicable (H1; H1-CA; H2)	•	•	•	•	•	•	•
A – AMP / 12V	•	•	•	•	•	•	•
B – AMP / 24 V	•	•	•	•	•	•	•
C – DIN / 12 V	•	•	•	•	•	•	•
D – DIN / 24 V	•	•	•	•	•	•	•
E – Deutsch / 12V	•	•	•	•	•	•	•
F – Deutsch / 24V	•	•	•	•	•	•	•
15 Response Orifices							
0 – Without response orifices	•	•	•	•	•	•	•
E – 1,0 mm	•	•	•	•	•	•	•
16 Purge Relief Valve							
0 – Without purge devices	•	•	•	•	•	•	•
A – 10 bar standard purge flow	•	•	•	•	•	•	•
B – 14 bar standard purge flow	•	•	•	•	•	•	•
C – 10 bar reduced purge flow	•	•	•	•	•	•	•
D – 14 bar reduced purge flow	•	•	•	•	•	•	•
E – 10 bar increased purge flow	•	•	•	•	•	•	•
F – Flow controlled 6 l/min (*o)	•	•	•	•	•	•	•
G – Blank plug instead of relief valve	•	•	•	•	•	•	•
17 Purge Shuttle Valve							
0 – Without purge devices	•	•	•	•	•	•	•
1 – Standard shuttle valve	•	•	•	•	•	•	•
2 – Damped shuttle valve	•	•	•	•	•	•	•
3 – Shuttle valve blocked	•	•	•	•	•	•	•
18 19 20 Minimum Displacement Setting							
000 -Catalog Pump Rating	•	•	•	•	•	•	•
— Numeric three digit, setting range see positions 4,5,6	•	•	•	•	•	•	•
21 22 23 Maximum Displacement Setting							
000 -Catalog Pump Rating	•	•	•	•	•	•	•
— Numeric three digit, setting range see positions 4,5,6	•	•	•	•	•	•	•
24 25 26 Pressure Override Setting							
000 -not applicable	•	•	•	•	•	•	•
— 190 -260 bar (Numeric 3 digits)	•	•	•	•	•	•	•
27 28 Special Requirements							
00 – Without (default)	•	•	•	•	•	•	•
AA – With special requirements	•	•	•	•	•	•	•
29 Surface Coating							
0 – Anti-rust conservation oil (default)	•	•	•	•	•	•	•
A – Primer blue	•	•	•	•	•	•	•
30 Unit Identification							
A – DuraForce	•	•	•	•	•	•	•
31 Type Code Release							
A – Revision Level	•	•	•	•	•	•	•

(*d) DIN porting only (see pos. 9) (*m) ISO metric porting only (see pos. 9)
(*o) open loop operation only (*p) radial service ports only (see pos. 10)

Model Code

HMR

Regulated Variable Displacement Motors (Open & Closed Loop Operation)

The following 36 digit coding system has been developed to identify preferred feature options for the Eaton Closed or Open Loop Hydraulic Motor. Use this code to specify a motor with the desired features. All 36-digits of the code must be present to release a new product number for ordering. Please contact your local customer service rep-representative for leadtime questions.

HMR			075			A	D	M	10		AP		0	E		0	0		00		0	0	0	000			000			000			00		0	AA	
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36		

	75	105	135	165	210	280
[1][2][3] Product						
HMR – Regulated Variable Displacement Motors	•	•	•	•	•	•
[4][5][6] Displacement						
075 – 075 cc	•					
105 – 105 cc		•				
135 – 135 cc			•			
165 – 165 cc				•		
210 – 210 cc					•	
280 – 280 cc						•
[7] Mounting Flange						
A – SAE J744 standard	•	•	•	•	•	•
P – Plug-in (*d)			•			
[8] Output Shaft						
C – Splined ANSI B92.1 8/16 - 15 teeth (SAE J744 F)						
D – Splined ANSI B92.1 12/24 - 14 teeth (SAE J744 C)			•			
J – Splined ANSI B92.1 8/16 - 13 teeth (SAE J744 D&E)				•	•	•
K – Splined ANSI B92.1 16/32 - 21 teeth	•	•				
L – Splined ANSI B92.1 16/32 - 23 teeth			•			
M – Splined ANSI B92.1 16/32 - 27 teeth				•	•	•
P – Shaft coupling flange size 4					•	•
[9] Porting						
M – ISO 6149 metric	•	•	•	•	•	•
[10] Port Orientation						
1 – Radial ports / without PTO	•	•	•	•	•	•
2 – Axial ports / without PTO	•	•	•	•		
4 – Radial ports / splined PTO shaft ANSI B92.1 16/32 - 21 teeth			•			
9 – Radial ports / PTO speed sensor 35 impulses			•			
[11] Attachments to Service Ports						
0 – Without	•	•	•	•	•	•
1 – Crossover relief block 250 bar (*p)				•	•	•
2 – Crossover relief block 300 bar (*p)				•	•	•
3 – Crossover relief block 380 bar (*p)				•	•	•
4 – Crossover relief block 420 bar (*p)				•	•	•
5 – Propel brake valve (wheeled applications) (*o)		•	•	•	•	•
6 – Propel brake valve (crawler applications) (*o)	•	•				
[12] Motor Operation						
A – Closed loop operation	•	•	•	•	•	•
B – Open loop operation	•	•	•	•	•	•
[13] Motor Control						
P – Pressure regulated	•	•	•	•	•	•
[14] Displacement Override						
0 – Without (*d)/(*o)	•	•	•	•	•	•
E – Electric	•	•	•	•	•	•
H – Hydraulic high pressure (*o)	•	•	•	•	•	•
L – Hydraulic low pressure (*o)	•	•	•	•	•	•
[15] Break Pressure Switching						
0 – None	•	•	•	•	•	•
E – Electric (*c)	•	•	•	•	•	•

	75	105	135	165	210	280
[16] Control Solenoids						
0 – not applicable	•	•	•	•	•	•
A – AMP / 12V	•	•	•	•	•	•
B – AMP / 24 V	•	•	•	•	•	•
C – DIN / 12 V	•	•	•	•	•	•
D – DIN / 24 V	•	•	•	•	•	•
E – Deutsch / 12V	•	•	•	•	•	•
F – Deutsch / 24V	•	•	•	•	•	•
[17] Response Orifices						
0 – Without response orifices	•	•	•	•	•	•
E – 1.0 mm	•	•	•	•	•	•
[18][19] Crossover Relief Valves Integrated						
00 – Without	•	•	•	•	•	•
AG – 350 bar (*q) / frame sizes 75;165: (*l)	•	•	•	•	•	•
AH – 420 bar (*q) / frame sizes 75;165: (*l)	•	•	•	•	•	•
[20] Purge Relief Valve						
0 – Without purge devices	•	•	•	•	•	•
A – 10 bar standard purge flow	•	•	•	•	•	•
B – 14 bar standard purge flow	•	•	•	•	•	•
C – 10 bar reduced purge flow	•	•	•	•	•	•
D – 14 bar reduced purge flow	•	•	•	•	•	•
E – 10 bar increased purge flow	•	•	•	•	•	•
F – flow controlled 6 l/min (*o)	•	•	•	•	•	•
G – blank plug instead of relief valve	•	•	•	•	•	•
[21] Purge Shuttle Valve						
0 – Without purge devices	•	•	•	•	•	•
1 – Standard shuttle valve	•	•	•	•	•	•
2 – Damped shuttle valve	•	•	•	•	•	•
3 – Shuttle valve blocked	•	•	•	•	•	•
[22] Brake / Counterbalance Valve Preparation						
0 – Without brake / counterbalance valve preparation	•	•	•	•	•	•
A – With propel brake valve preparation (*o)		•	•	•	•	•
[23][24][25] Minimum Displacement Setting						
000 – Catalog Pump Displacement	•	•	•	•	•	•
— – Numeric 3 digits, setting range see pos. 2	•	•	•	•	•	•
[26][27][28] Maximum Displacement Setting						
000 – Catalog Pump Displacement	•	•	•	•	•	•
— – Numeric 3 digits, setting range see pos. 2	•	•	•	•	•	•
[29][30][31] Pressure Override Setting						
000 – Not applicable	•	•	•	•	•	•
— – 190 - 260 bar (numeric 3 digits)	•	•	•	•	•	•
[32][33] Special Requirements						
00 – Without (default)	•	•	•	•	•	•
[34] Surface Coating						
0 – Anti-rust conservation oil (default)	•	•	•	•	•	•
A – Primer blue	•	•	•	•	•	•
[35] Unit Identification						
A – DuraForce	•	•	•	•	•	•
[36] Type Code Release						
A – Revision Level	•	•	•	•	•	•

(*d) DIN porting only (see pos. 22),

(*m) ISO metric porting only (see pos. 22)

(*o) open loop operation only (see pos. 12),

(*c) closed loop operation only (see pos. 12), (*p)

radial service ports only (see pos. 10),

(*l) axial service ports only (see pos. 10),

(*q) Without purging devices only (see pos. 20 & 21)

• Available Option • Preferred Option

Model Code

HMF

Fixed Displacement Motors
(Open & Closed Loop Operation)

The following 21 digit coding system has been developed to identify preferred feature options for a HMF Closed or Open Loop Hydraulic Motor. Use this code to specify a motor with the desired features. All 21-digits of the code must be present to release a new product number for ordering. Please contact your local customer service representative for leadtime questions.

HMF			063			B		C		M		R		0		00		0		00		0		A		A	
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21							

	28	35	50	55	63	75	105	135		28	35	50	55	63	75	105	135
1 2 3 Product									14 Purge Relief Valve								
HMF – Fixed Displacement Motors	•	•	•	•	•	•	•	•	0 – Without purge devices	•	•	•		•	•	•	•
4 5 6 Displacement									A – 10 bar standard purge flow	•	•	•	•	•	•	•	•
028 – 28 cc	•								B – 14 bar standard purge flow	•	•	•	•	•	•	•	•
035 – 35 cc		•							C – 10 bar reduced purge flow	•	•	•	•	•	•	•	•
050 – 50 cc			•						D – 14 bar reduced purge flow	•	•	•	•	•	•	•	•
055 – 55 cc				•					E – 10 bar increased purge flow	•	•	•	•	•	•	•	•
063 – 63 cc					•				F – Flow controlled 6 l/min (open loop only)	•	•	•	•	•	•	•	•
075 – 75 cc						•			G – Blank plug instead of relief valve	•	•	•	•	•	•	•	•
105 – 105 cc							•										
135 – 135 cc								•	15 Purge Shuttle Valve								
7 Mounting Flange									0 – Without purge devices	•	•	•		•	•	•	•
B – SAE B, 2-Bolt	•	•							1 – Standard shuttle valve	•	•	•	•	•	•	•	•
C – SAE C, 2-Bolt			•	•	•	•	•		2 – Damped shuttle valve	•	•	•	•	•	•	•	•
D – SAE D, 2-Bolt								•	3 – Shuttle valve blocked	•	•	•	•	•	•	•	•
8 Output Shaft									16 Speed Sensor in Motor Housing								
C – Splined ANSI B92.1 16/32 - 15 teeth (SAE J744 B-B)	•	•							0 – Without	•	•	•	•	•	•	•	•
D – Splined ANSI B92.1 12/24 - 14 teeth (SAE J744 C)			•	•	•	•	•		A – 7 impulses		•	•					
J – Splined ANSI B92.1 8/16 - 13 teeth (SAE J744 D&E)								•	B – 9 impulses					•			
K – Splined ANSI B92.1 16/32 - 21 teeth			•	•	•	•	•		17 18 Special Requirements								
L – Splined ANSI B92.1 16/32 - 23 teeth								•	00 – Without (default)	•	•	•	•	•	•	•	•
M – Splined ANSI B92.1 16/32 - 27 teeth								•	19 Surface Coating								
9 Porting									0 – Anti-rust conservation oil (default)	•	•	•	•	•	•	•	•
M – ISO 6149 metric	•	•	•	•	•	•	•	•	A – Primer blue	•	•	•	•	•	•	•	•
10 Port Orientation									20 Unit Identification								
R – Side Ports	•	•	•	•	•	•	•	•	A – DuraForce	•	•	•	•	•	•	•	•
L – End Ports				•	•	•	•	•	21 Type Code Release								
11 Attachments to Service Ports									A – Revision Level	•	•	•	•	•	•	•	•
0 – Without	•	•	•	•	•	•	•	•									
12 13 Crossover Relief Valves Integrated																	
00 – Without	•	•	•	•	•	•	•	•									
AA – Single-stage 210 bar (*p)/(*q)	•	•			•	•	•	•									
AC – Single-stage 250 bar (*p)/(*q)	•	•			•	•	•	•									
AG – Single-stage 350 bar (*p)/(*q)	•	•			•	•	•	•									
AE – Single-stage 420 bar (*p)/(*q)	•	•			•	•	•	•									
AP – Two-stage 200/380 bar (*p)/(*q)	•	•			•	•	•	•									

- Available Option
- Preferred Option
- ♦ Separate Specification Required

- (*o) open loop operation only
- (*p) radial service ports only (see pos. 10)
- (*q) without purging devices only (see pos. 14 & 15)

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Model Code

HMA

Adjustable Fixed Displacement Motors
(Open & Closed Loop Operation)

The following 21 digit coding system has been developed to identify preferred feature options for a HMA Closed or Open Loop Hydraulic Motor. Use this code to specify a motor with the desired features. All 21-digits of the code must be present to release a new product number for ordering. Please contact your local customer service representative for leadtime questions.

HMA			165			A	C	M	R	0	0	0	000	00	0	A	A			
┌───┐			┌───┐			┌─┐	┌─┐	┌─┐	┌─┐	┌─┐	┌─┐	┌─┐	┌───┐		┌─┐	┌─┐	┌─┐			
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21

	75	105	135	165	210	280		75	105	135	165	210	280
1 2 3 Product													
HMA – Adjustable Fixed Displacement Motors				•	•						•	•	
4 5 6 Displacement													
165 – 165 cc				•									
210 – 210 cc					•								
7 Mounting Flange													
A – SAE J744 standard				•	•								
8 Output Shaft													
C – splined ANSI B92.1 8/16 – 15 teeth (SAE J744 F)					•								
D – splined ANSI B92.1 12/24 – 14 teeth (SAE J744 C)													
J – splined ANSI B92.1 8/16 – 13 teeth (SAE J744 D&E)				•									
K – splined ANSI B92.1 16/32 – 21 teeth													
M – Splined ANSI B92.1 16/32 – 27 teeth				•	•								
9 Porting													
M – ISO 6149 metric				•	•								
10 Port Orientation													
R – Radial ports / Without PTO				•	•								
11 Attachments to Service Ports													
0 – Without				•	•								
1 – Crossover relief block 250 bar (*p)				•	•								
2 – Crossover relief block 300 bar (*p)				•	•								
3 – Crossover relief block 380 bar (*p)				•	•								
4 – Crossover relief block 420 bar (*p)				•	•								
12 Purge Relief Valve													
0 – Blank plug instead of relief valve				•	•								
A – 10 bar standard purge flow				•	•								
B – 14 bar standard purge flow				•	•								
C – 10 bar reduced purge flow											•	•	
D – 14 bar reduced purge flow											•	•	
E – 10 bar increased purge flow											•	•	
F – Flow controlled 6 l/min (*o)											•	•	
13 Purge Shuttle Valve													
0 – Shuttle valve blocked											•	•	
1 – Standard shuttle valve											•	•	
2 – Damped shuttle valve											•	•	
14 15 16 Displacement Setting													
000 Standard Displacement											•	•	
--- 135 - 165 cc (numeric 3 digits), setting range see positions 4,5,6											•	•	
--- 165 - 210 cc (numeric 3 digits), setting range see positions 4,5,6											•	•	
17 18 Special Requirements													
00 – Without (default)											•	•	
19 Surface Coating													
0 – Anti-rust conservation oil (default)											•	•	
A – Primer blue											•	•	
20 Unit Identification													
A – DuraForce											•	•	
21 Type Code Release													
A – Revision Level											•	•	

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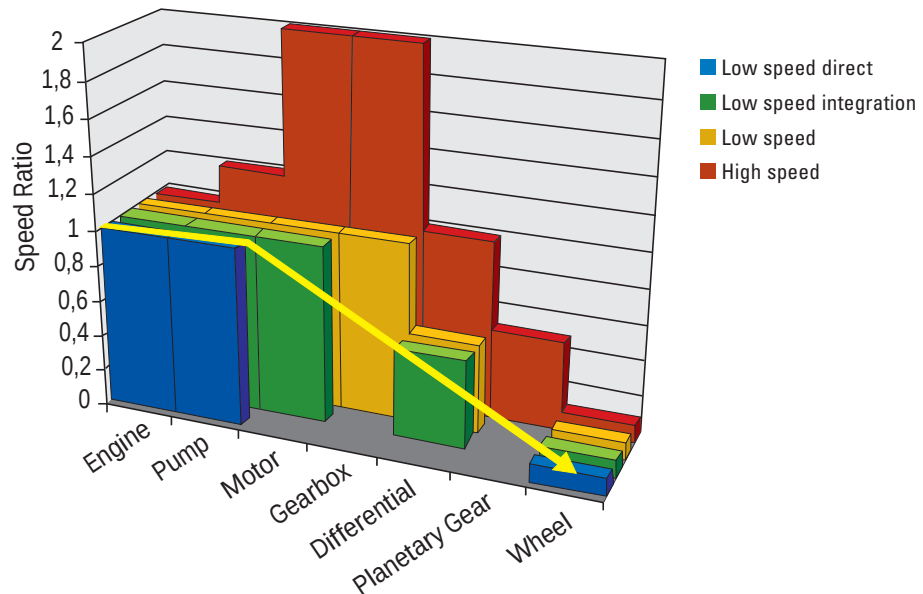
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- Available Option
- Preferred Option
- ◆ Separate Specification Required

- (*o) open loop operation only
- (*p) radial service ports only (see pos. 10)

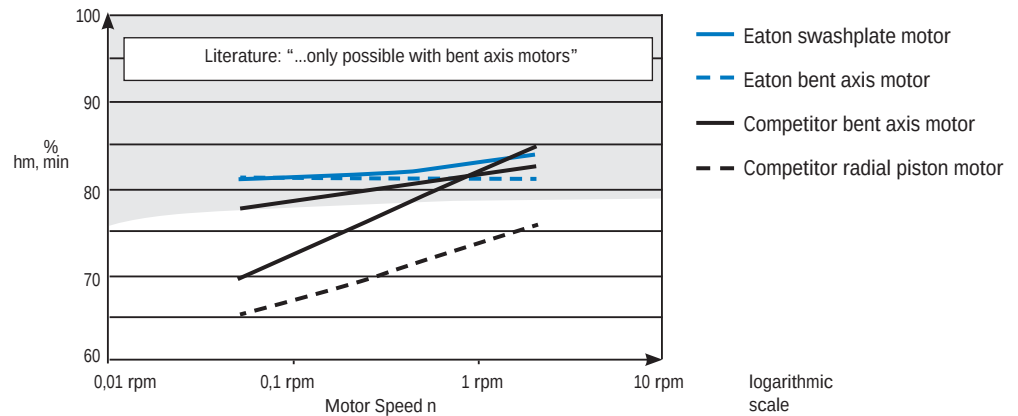
Equipment manufacturers profit by the Eaton transmission concept. Due to the direct conversion of the prime mover speed into wheel speed it is possible to reduce the number of drive line components and the energy losses in the operating cycle.

Speed Steps of Transmission Concepts



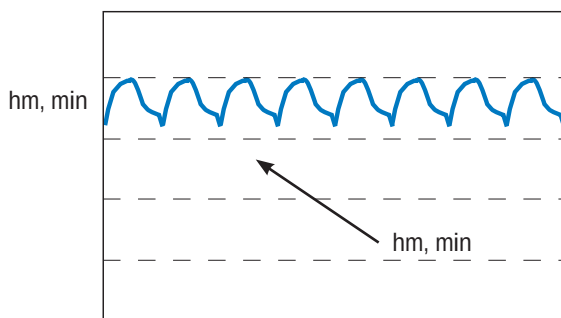
Starting Torque

Eaton hydraulic motors offer uniformly high torque for smooth start up. Right from the start.

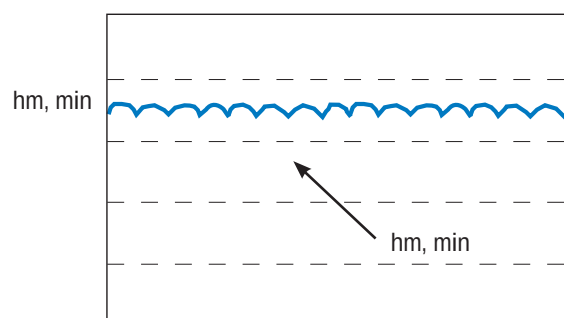


Torque at 350 bar and 2 rpm

of a bent axis motor



of a swashplate motor



Operational Parameters

Lifetime Recommendations

Eaton high pressure units are designed for excellent reliability and long service life. The actual service life of a hydraulic unit is determined by numerous factors. It can be extended significantly through proper maintenance of the hydraulic system and by using high-quality hydraulic fluid.

Beneficial Conditions For Long Service Life

Speed	Lower continuous maximum speed
Operating Pressure	Less than 300 bar Δp on average
Maximum Pressure	Only at reduced displacement
Viscosity	15 ... 30 cSt
Power	Continuous power or lower
Purity of Fluid	18/16/13 in accordance with ISO 4406 or better

Adverse Factors Affecting Service Life

Speed	Between continuous maximum speed and intermittent maximum speed
Operating Pressure	More than 300 bar Δp on average
Viscosity	Less than 10 cSt
Power	Continuous operation close to maximum power
Purity of Fluid	Lower than 18/ 16/ 13 in accordance with ISO 4406

Operational parameters. Filtration

In order to guarantee long-term proper function and high efficiency of the hydraulic pumps the cleanliness level of the lubricant must comply with the following criteria according to

Eaton Hydraulic Fluid Recommendation 03-401-2010. Maintaining the recommended cleanliness level can extend the service life of the hydraulic system significantly.

For reliable proper function and long service life

18/16/13 in accordance with ISO 4406 or better

Commissioning

The minimum cleanliness level requirement for the hydraulic oil is based on the most sensitive component. For commissioning we recommend a filtration in order to achieve the required cleanliness level.

Filling and operation of hydraulic systems

The required cleanliness level of the hydraulic oil must be ensured during filling or topping up. When drums, canisters, or large-capacity tanks are used the oil generally has to be filtered. We recommend the implementation of suitable filters to ensure that the required cleanliness level of the oil is achieved and maintained during operation.

International standard

Code number according to ISO 4406

18/16/13

Filtration

For Reliable Proper Function and Long Service Life	18/16/13 in accordance with ISO 4406 or better
Minimum Requirements	20/18/15 in accordance with ISO 4406
Commissioning	The minimum purity requirement for the hydraulic oil is based on the most sensitive system component. For commissioning we recommend a filtration in order to achieve the required purity.
Filing in Operation of Hydraulic Systems	The required purity of the hydraulic oil must be ensured during filling or topping up. When drums, canisters or large-capacity tanks are used the oil generally has to be filtered. We recommend the implementation of suitable measures (e.g. filters) to ensure that the required minimum purity of the oil is also achieved during operation
International Standard	Code number according to ISO 4406 purity class according to SAE AS 4059 18/16/13 corresponds to 8A/7B/7C 20/18/15 9A/8B/8C

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Operational Parameters

Pressure Fluids

In order to ensure the functional performance and high efficiency of the hydraulic motors the viscosity and purity of the operating fluid should meet the different operational requirements. Eaton recommends using only hydraulic fluids which are confirmed by the manufacturer as suitable for use in high pressure hydraulic installations or approved by the original equipment manufacturer.

Permitted Pressure Fluids

- Mineral oil HLP to DIN 51 524-2
- Biodegradable fluids in accordance with ISO 15 380 on request
- Other pressure fluids on request

Eaton offers an oil testing service in accordance with VDMA 24 570 and the test apparatus required for in-house testing. Prices available on request.

Recommended Viscosity Ranges

Pressure Fluid Temperature Range	[°C]	-20 to +90
Working viscosity range	[mm ² /s] = [cSt]	10 to 80
Optimum working viscosity	[mm ² /s] = [cSt]	15 to 30
Max. viscosity (short time start up)	[mm ² /s] = [cSt]	1000

In order to be able to select the right hydraulic fluid it is necessary to know the working temperature in the hydraulic circuit. The hydraulic fluid should be selected such that its optimum viscosity is within

the working temperature range (see tables).

The temperature should not exceed 90°C (194°F) in any part of the system. Due to pressure and speed influences the

leakage fluid temperature is always higher than the circuit temperature. Please contact Eaton if the stated conditions cannot be met in special circumstances.

Viscosity Recommendations

Working Temperature	Viscosity Class
Temperature	[mm ² /s] = [cSt] at 40°C (104°F)
Approx. 30 to 40°C (86 to 104°F)	22
Approx. 40 to 60°C (104 to 140°F)	32
Approx. 60 to 80°C (140 to 176°F)	46 or 68

Further information regarding installation can be found in the operating instructions.

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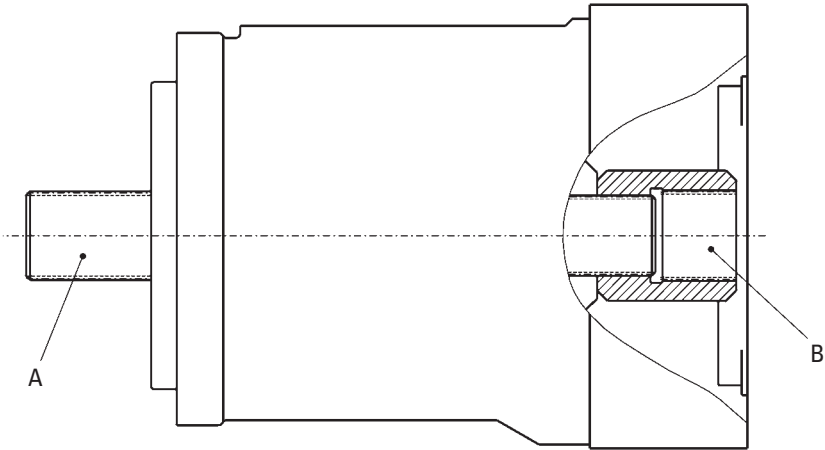
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Torque Transmission

Mounting Flange

Depending on the selected components, different torques may be transferred. Please ensure that the load transfer components such as mounting flange and PTO through-shaft are designed adequately. Our sales engineers will be pleased to provide design advice.

Torque Transmission of HMF / A / V / R



The diagram Torque transmission of HMF / A / V / R shows the output side (A) and the PTO through-shaft (B) of a motor.

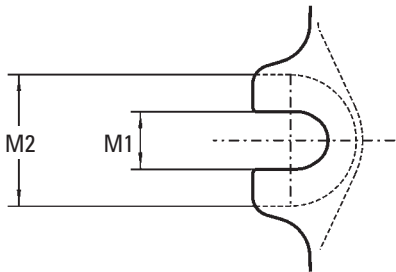
The information on the following pages refers to:

- Mounting flange and drive shaft (A)
- PTO flange and through shaft (B)

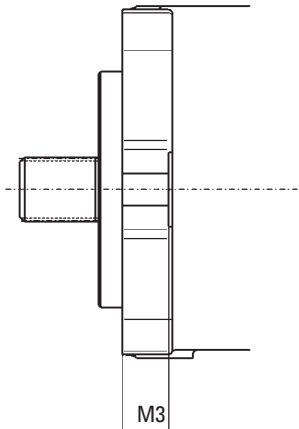
A) Flange Profile

Bolt Hole Dimensions	Rated Size HMF / A / V / R								
	Dim.	50/55	75	105	135	165	210	280	135D
M1 Inside Diameter	mm	17.5	17.5	17.5	1.5	21.5	22.0	22.0	21.5
M2 Outside Diameter	mm	40.0	34.0	34.0	40.0	40.0	—	—	40.0
M3 Length	mm	20.0	20.0	20.0	20.0	25.0	30.0	30.0	20.0

Bolt Hole Diameter



Bolt Hole Length



Torque Transmission

Mounting Flange

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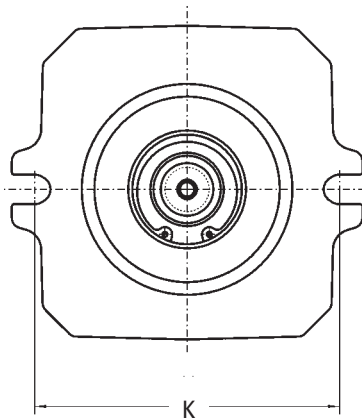
A) Mounting Flange Dimensions

Rated Size HMF / A / V / R

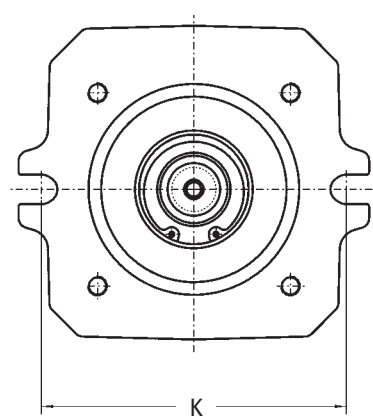
Mounting Flange Dimensions in Accordance/SAE J744	Dim. K (mm)	28/35	55	75	105	135	165	210	280	135D
SAE B, B-B	146.0	x								
SAE C, C-C 2-hole	181.0		x	x	x					
SAE D 2-hole	228.6					x	x			
SAE D 2-hole with 4 additional threaded holes	228.6									x
SAE D 2-hole with 4 additional bolt holes	228.6									x
SAE E 4-hole	224.5							x	x	
Plug-in housing with 2 hole flange (not for HMF)	224.0			x						
Plug-in housing not for HMF	251.8				x	x				

A) Fixing Hole Distance K

2-hole Flange



2-hole Flange with 4 Additional Threaded Holes



Torque Transmission

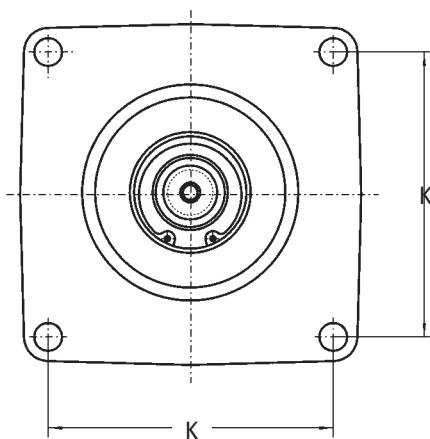
Mounting Flange

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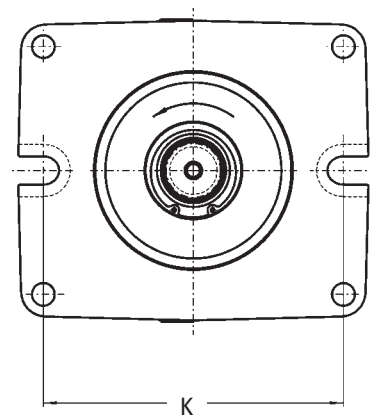
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A) Fixing Hole Distance K (continued)

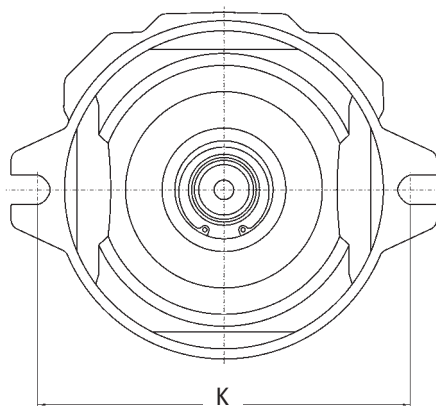
4-hole Flange



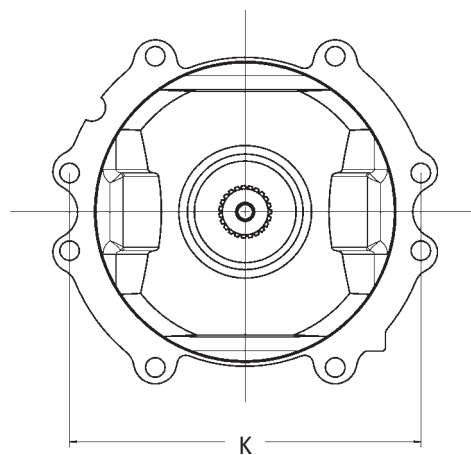
2-hole Flange with
4 Additional Bolt Holes



Plug-in Housing with
2-hole Flange



Plug-in Flange



Torque Transmission

Drive Shaft

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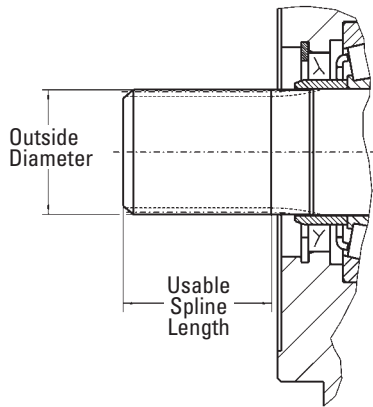
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A) Dimensions – Drive Shafts

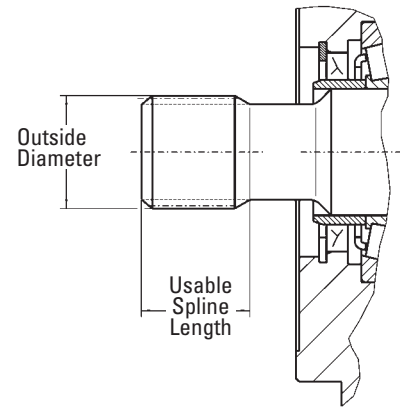
Shift Spline (in accordance with ANSI B92.1)	SAE J744 Code for Centering and Shaft	Outside Diameter	Usable Spline Length	Shaft Type	Available for Rated Size								
					(mm)	(mm)	28/35	50/55	75	105	135	165	210
16/32, 15 t	B-B	24.98	29	1	x								
16/32, 21 t		34.51	39.5	1		x	x						
16/32, 23 t		37.68	38.5	1				x					
16/32, 27 t		44.05	62	1					x	x			x
12/24, 14 t	C	31.22	30	2				x					
8/16, 13 t	D/E	43.71	50	2					x HMF	x			
8/16, 15 t	F	50.06	58	1							x	x	

A) Eaton Hydraulics Shaft Types

Type 1 without Undercut



Type 2 with Undercut



A) + B) Output Shaft Torque

The transferable torque of the drive shaft at PTO through-shaft (B) corresponds to the torque of the drive shaft (A).

Rated Size		28/35	50/55	75	105	135	165	210	280	135D
Continuous Torque	Nm	114/142	199/218	302	418	540	657	836	1114	1075
Maximum Torque	Nm	191/238	334/366	508	702	907	1104	1404	1872	1803

Torque Transmission

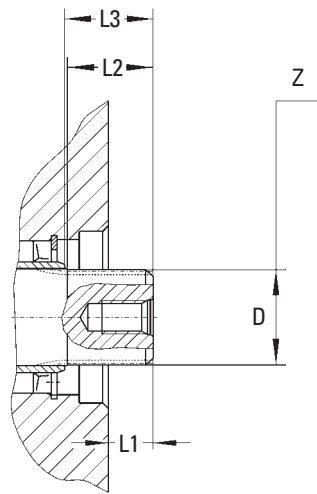
PTO Through-Drive Motor

Based on a standard Eaton variable hydraulic motor with single shaft end, the PTO Through-Drive Motor features two shaft ends for torque transfer. This enables the hydraulic motor to be installed directly in the drive line without transfer gearbox, reducing noise emission and fuel consumption. At the same time the overall efficiency increases.

B) PTO Dimensions for HMV

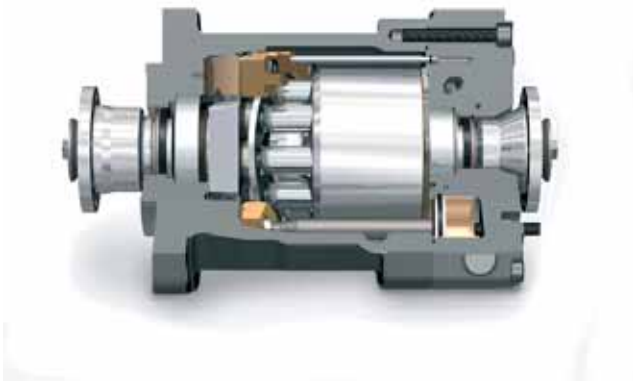
Rated Size	Dim	105	135	165	210	280
Z Drive Shaft Profile In Accordance with ANSI B92.1	mm	16/32, 19 t	16/32, 21 t	16/32, 22 t	16/32, 24 t	16/32, 27 t
D Shaft Diameter	mm	31.2	34.51	36.05	39.27	44.05
L1 Shaft End Length-Housing	mm	30.1	16.2	-0.5	20.9	180
L2 Usable Spline Length	mm	41.5	31.0	31.0	44.0	47.0
L3 Bearing Stop	mm	49.6	32.0	32.8	57.2	62.0

B) PTO Dimensions



PTO Through-Drive Motor with Coupling Flanges

For a direct installation
into the drive line



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Functions – Overview

Closed Loop Circuit

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Closed Loop Circuit

Servo Pressure Supply			Purge and Case Flushing			Crossline Relief Protection			Brake Pressure Shut Off		Speed Sensor			
	External	Internal From Low Pressure	Internal From High Pressure	Without	Standard 10 L/Min	Reduced 5 L/Min	Without	Fixed	Dual Setting	Without	With	Without	With	
HMF				On Request	●	○	○	o.r.		○		○	○	
HMF P					●	○	○	o.r.		○		○	○	
HMA					●	○	○			○		○	○	
HMV H1	●	○			●	○	○				○		○	○
HMV H2	●	○			○	○	○				○		○	○
HMV E1	●	○			●	○	○				○		○	○
HMV E2	●	○			●	○	○				○		○	○
HMV EH1P		○			●	○ at 20 bar supply pressure, 14 bar CBV	○					○	○	
HMR pneumatic Vmax control					●	○	○	○				○	○	○
HMR hydraulic Vmax control; low pressure					●	○	○	○				○	○	○
HMR hydraulic Vmax control; high pressure				●	○	○	○				○	○	○	
HMR electric Vmax control				●	○	○	○				○	○	○	

● Standard ○ Option

Functions – Overview

Closed Loop Circuit

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Closed Loop Circuit

	Servo Pressure Supply	Purge and Case Flushing		Crossline Relief Protection			Counterbalance Valve		Speed Sensor	
	Internal From High Pressure	Without	Flow Control	Without	Fixed	Dual Setting	Without	With	Without	With
HMF		●	○	○	o.r.	o.r.	○		○	○
HMF P		●	○	○	o.r.	○	○		○	○
HMA		●	○	○			○		○	○
HMV H1		●	○	○			○		○	○
HMV H2	○	●	○	○			○		○	○
HMV E1		●	○	○			○		○	○
HMV E2	○	●	○	○			○		○	○
HMV EH1P	○	●	○	○	○		○	○	○	○
HMR pneumatic V _{max} control	○	●	○	○	○		○	○	○	○
HMR hydraulic V _{max} control; low pressure	○	●	○	○	○		○	○	○	○
HMR hydraulic V _{max} control; high pressure	○	●	○	○	○		○	○	○	○
HMR electric V _{max} control	○	●	○	○	○			○	○	○

● Standard ○ Option

Functions – Purge and Case Flushing

Purge Flow in Closed Loop Circuit

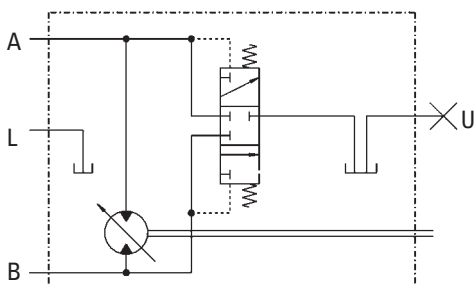
Purge and case flushing is used

- for reducing the temperature of the motor and the system in the open and closed loop circuits
- for replacing the oil in the circuit
- to enhance filtration and
- for removing air from the system

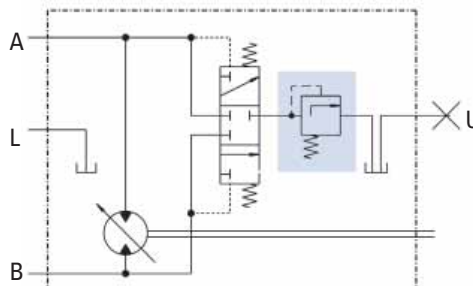
For equipment options for Eaton motors please refer to the function overview.

Version	Purge Valve CBV Setting Pressure	Diagram	Sizes 28–135	Sizes 165–280
Standard	10 bar with 19 bar feed pressure	2	16.0 l	18.0 l
Standard	14 bar with 19 bar feed pressure	2	8.0 l	10.0 l
Restricted with 2.5 mm orifice	10 bar with 19 bar feed pressure	3	6.5 l	7.5 l
Restricted with 2.5 mm orifice	14 bar with 19 bar feed pressure	3	4.5 l	5.5 l
Increased	10 bar with 30 bar feed pressure	2	28.0 l	30.0 l
Increased	14 bar with 30 bar feed pressure	2	25.0 l	27.0 l

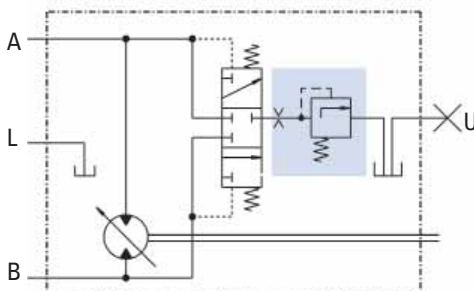
**Purge Valve 1
without (0 l/min)**



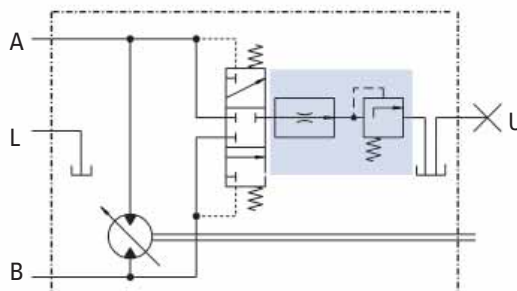
**Purge Valve 2
Standard and Increased**



**Purge Valve 3
Restricted**



**Purge Valve 4
Flow Controlled**



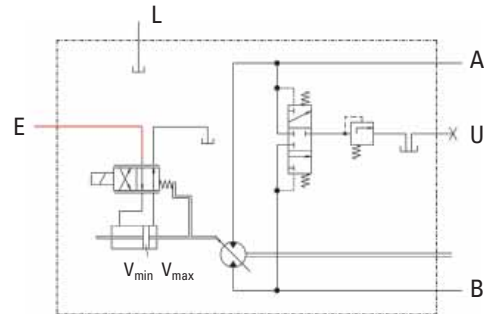
Flow-controlled purge flushing in an open loop circuit approx. 4 l/min at 5 bar set pressure (independent of low pressure) diagram 4

Servo supply pressure delivers the force needed to change the position of the swash plate in variable displacement and pressure regulated motors. For equipment options for Eaton motors please refer to the function overview.

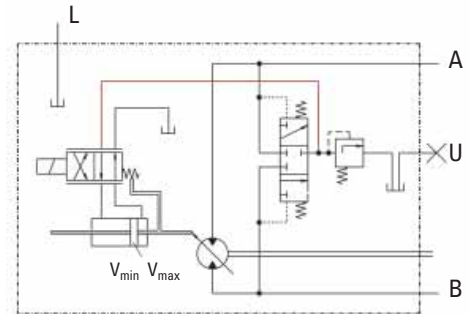
Functions – Servo Supply Pressure Feed

For HMV
Variable Motors

External Supply

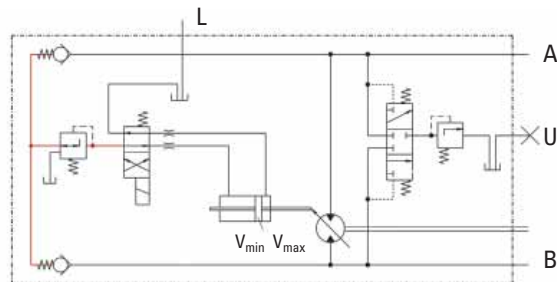


Internal Supply. Purge Circuit



For HMR
Regulating Motors

Internal Supply.
High Pressure Circuit

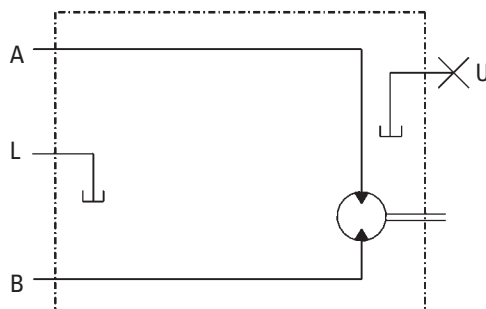


Functions – Crossline Relief (Secondary) Protection

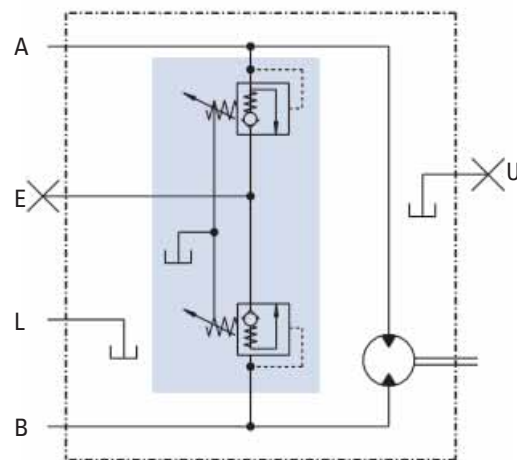
The secondary valves (crossline relief valves) protect the system from pressure overload by using two interlinked pressure relief valves (combined with check valves). It is recommended for applications where this protective function is not provided by other means (e.g. through primary protection at the pump or LS valves). The secondary protection includes a make up function. It prevents cavitation and is required in an open loop circuit if the motor requires more oil than is supplied. For special situations like in the swing gear drive the installation of controllable secondary valves is recommended. For equipment options for Eaton motors please refer to the function overview.

Secondary Protection

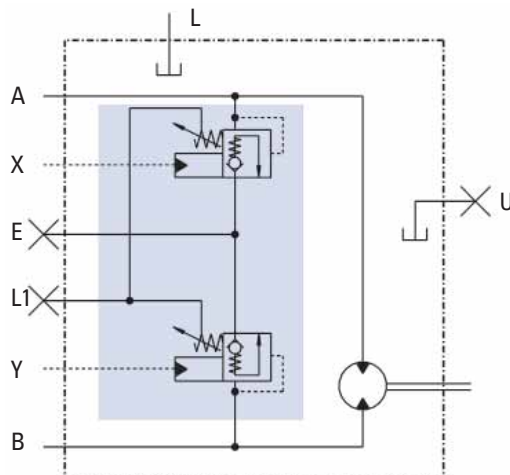
Without Crossline Relief Valve



With Crossline Relief Valve Protection



With Dual Pressure Crossline Relief Valve Protection



- A, B Work ports
- L, L1, U Case drain / vent connections
- X, Y Control connection for dual pressure crossline relief valve
- E Make up connection

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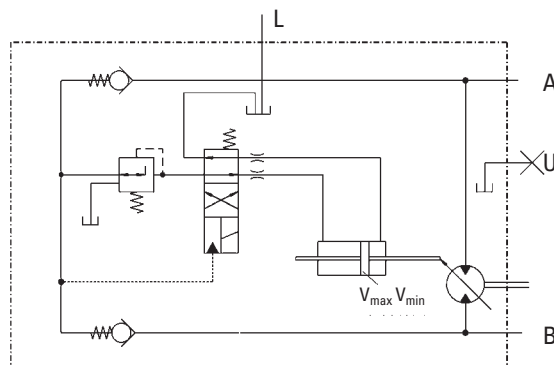
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Functions – Brake Pressure Shut Off

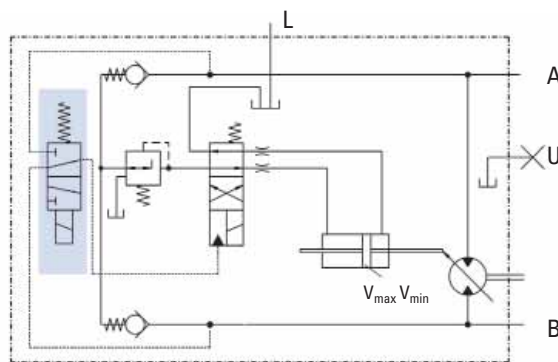
Pressure regulated motors shift to maximum displacement at high operating pressure, irrespective of which side is under pressure and in propel situations this can have undesirable effects. For example, if the motor shifts to maximum displacement during the transition phase from downhill travel (low system pressure) to overrun (high pressure on the reverse side) an extremely strong vehicle braking effect will occur. The brake pressure shut off valve prevents the regulator being subjected to this braking pressure and, therefore, ensures that the motor remains at minimum displacement. For equipment options for Eaton motors please refer to the function overview.

Brake Pressure Shut Off

Without Brake Pressure Shut Off



With Brake Pressure Shut Off



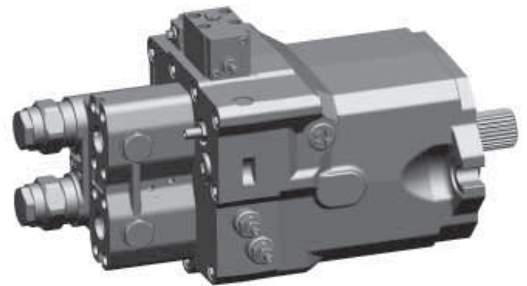
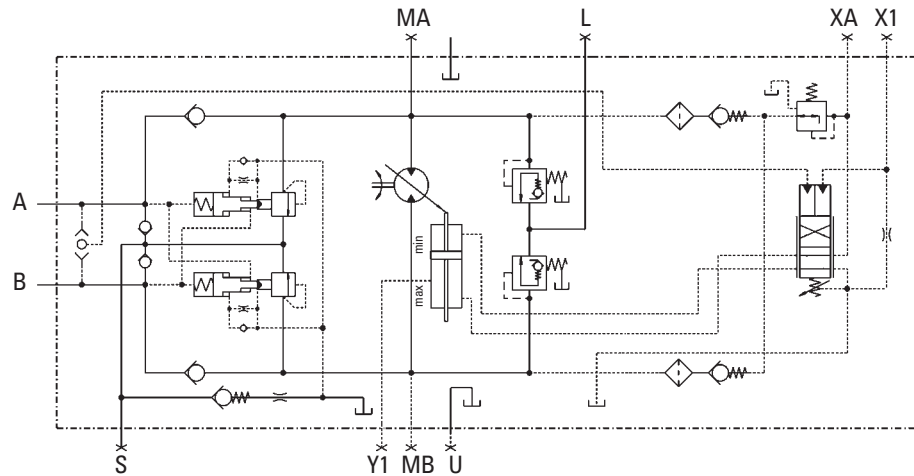
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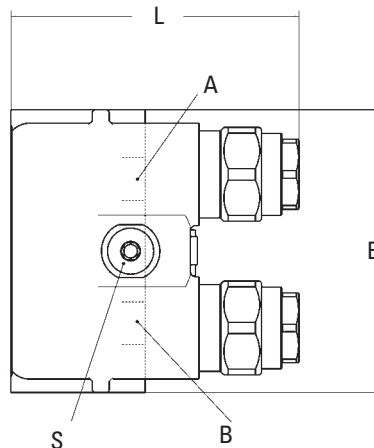
Functions – Counterbalance Valve

The counterbalance (brake) valve prevents the motor over speeding during an over-run situation. To achieve this, the motor return flow is automatically and continuously metered such that it always matches the input flow. Different braking responses are possible. The integrated make-up function simultaneously prevents cavitation. A purge and case flushing function is also integrated. Counterbalance (brake) valves are typically used for drive systems in open loop circuits. Further types of counterbalance valves are shown in section Dimensions. HMR.

**With Counterbalance
(Brake) Valve,
Here: Axial Attachment**



Dimensions



Brake Valve	1"	1 1/4"
Length L	168.5	168.5
Width B	165.7	195
Height	136.6	143

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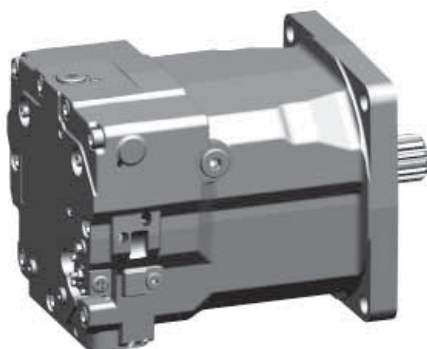
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Functions – Speed Sensor

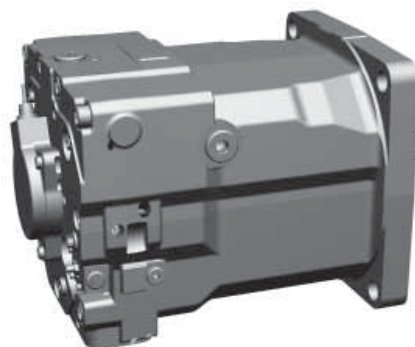
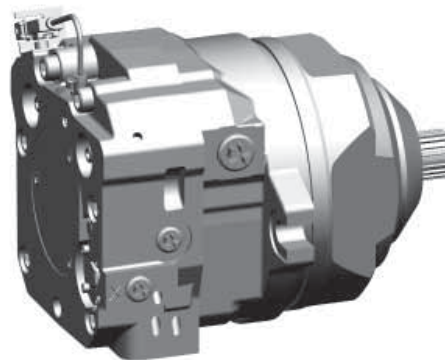
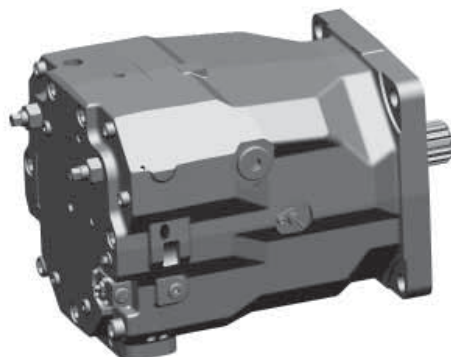
Speed sensors electronically register the motor speed and send an associated input signal to electronic drive controls.

Speed Sensor

Without Speed Sensor



With Speed Sensor



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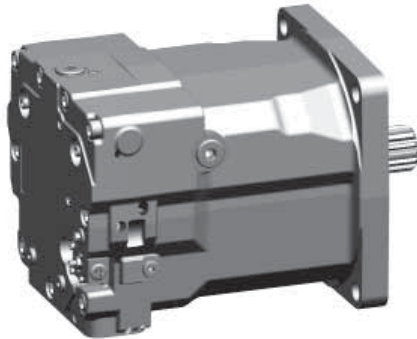
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Motor Types

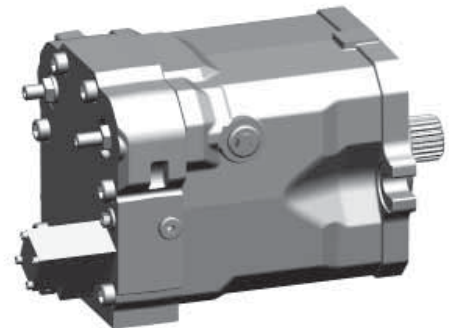
Based on the respective system requirements, Eaton offers fixed displacement, variable displacement and regulating motors with high starting torque for open and closed loop operation. Optional auxiliary functions, zero displacement capacity and PTO through-shaft enable higher machine design flexibility and increase the efficiency of the travel drive. The motors are optionally controlled electrically, hydraulically or pneumatically.

Motor Type	Control/Function	Product Name
Fixed Displacement Motor		HMF
	With Swing Drive Function	HMF P
	Displacement Adjustable	HMA
Regulating Motor	V _{max} Pneumatic	HMR
	V _{max} Hydraulic, Low Pressure	HMR
	V _{max} Hydraulic, High Pressure	HMR
	V _{max} Electric	HMR
Variable Displacement Motor	Stepless Variable Control, Hydraulic	HMV H1
	Stepless Variable Control, Electric	HMV E1
	Two Position Control (Flip-Flop), Hydraulic	HMV H2
	Two Position Control (Flip-Flop), Electric	HMV E2
	Stepless Variable Control with Pressure Override	HMV EH1P

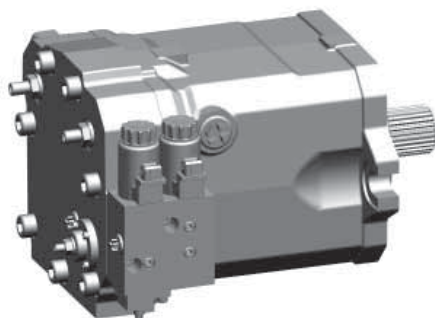
HMV H



HMV E



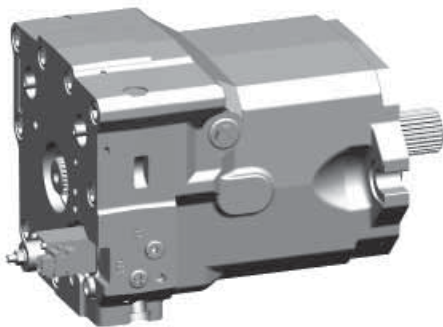
HMV EH1P



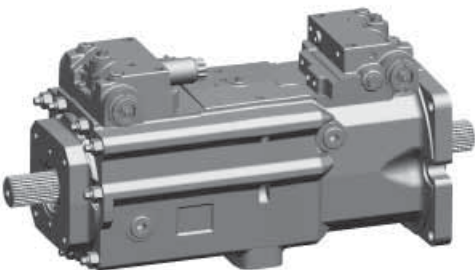
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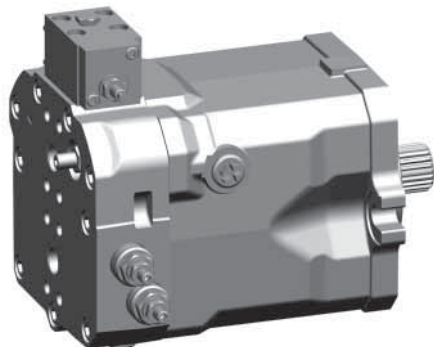
HMV PTO



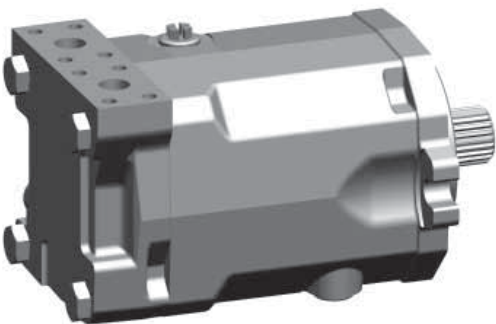
HMV D



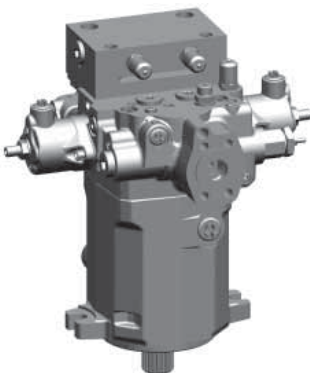
HMR



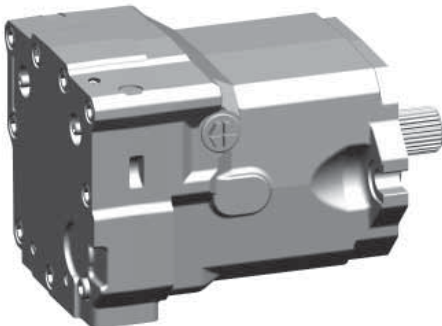
HMF



HMF P



HMA



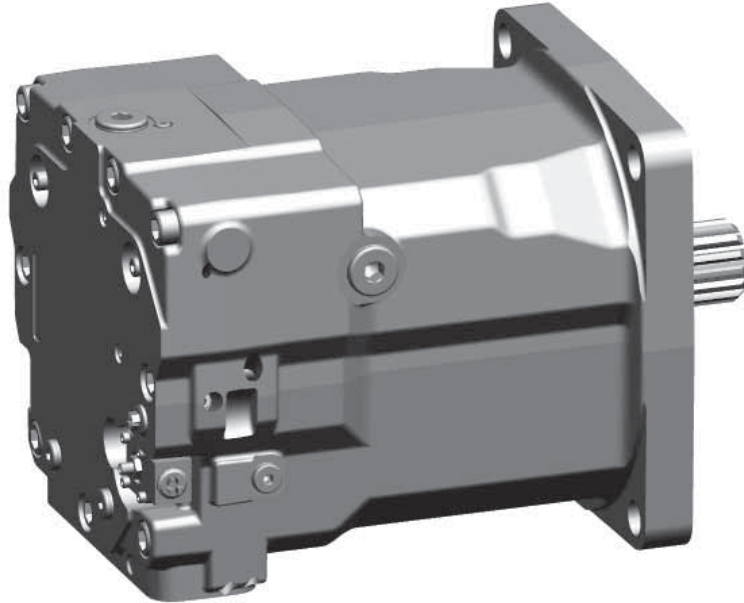
Motor Types – HMV

Variable Displacement Motor

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HMV Variable Displacement Motor



Features

- Stepless or two position control
- Electric or hydraulic control
- Override pressure control possible
- Brake pressure shut off possible
- Can be set to 0 cm³/rev
- Double motor available

Benefits

- Smooth low-speed operation
- High starting torque
- Wide torque / speed conversion range
- Highly dynamic response characteristics
- Compact design
- High power density
- High reliability
- Long service life
- Simplified drive line

Motor Types – HMV

H1 and E1 Stepless Variable Control

Motors with stepless variable control are suitable for open and closed loop circuit. Without control signal they shift to maximum displacement V_{max} . Displacement control is hydraulic or via an electric proportional control signal. Servo pressure supply is optionally internal or external, see section Functions. Servo pressure supply. The following data are independent of the nominal motor size.

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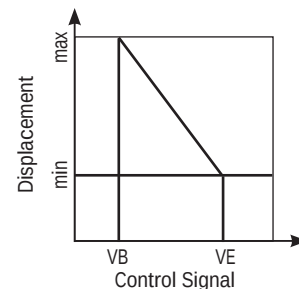
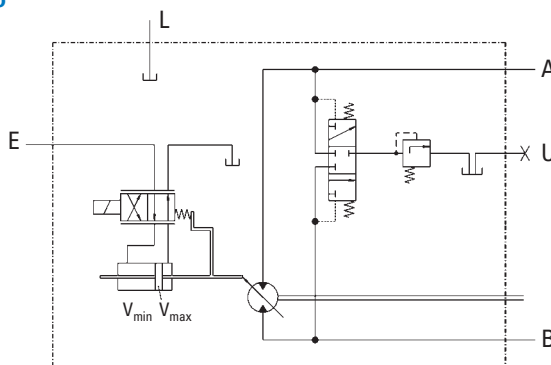
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Stepless Variable Control Features

External Servo Pressure Supply	Minimum Tripping	bar	20
	Maximum Permissible	bar	40
Hydraulic Control If V_{max} , Eff > V_{min} , Nominal, is the Resolution Lower	Control Range	bar	=6
	Control Begin	bar	7, 8, 9 or 9.5
	Maximum Permissible Pressure	bar	40
Electric Control	Connector Type	Hirschmann, AMP Junior Timer, 2-pin	
	Rated Voltage = Max. Continuous Voltage	V	12 24
	Voltage Type	DC voltage	
	Power Input	W	15.6
	Rated Current = Max. Continuous Current	mA	1300
	Control Current	Swash Begin	mA 450 225
		Swash End	mA 1200 600
	Relative Duty Cycle	%	100
	Protection Class	IP 6K6K, part 9	
	Control Types	Digital Control Via Pulse Width Modulation Pwm With Eaton Transducers	
		Analog Control with Alternative Transducers	
		100 Hz rectangle, Pulse duty ratio variable over control range	
		Direct current (With or without superimposed dither signal for stability and reducing hysteresis, dither: ± 125 mA, 32-40 Hz, duty cycle ratio 1:1)	
Minimum Response Time with Standard Orifice with 20 Bar Servo Pressure		s	0.5

Stepless Variable Motor with Electric Displacement Control and External Servo Supply Pressure

- A,B Work port connections
- L,U Case drain / vent connection
- E Servo supply pressure connections
- VB Swash begin
- VE Swash end



Two position motors are suitable for open and closed loop operation. Without control signal they are set to maximum displacement V_{max} . Adjustment between V_{min} and V_{max} is smooth and with short response time. The required switching signal can optionally be hydraulic or electric, the servo pressure supply internal or external, see section Functions. Servo pressure supply. The following data are independent of the rated motor size.

Motor Types – HMV

H2 and E2 Two Position

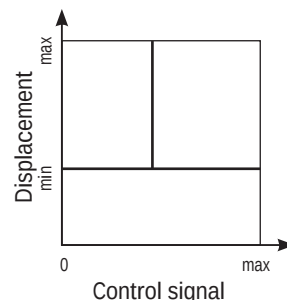
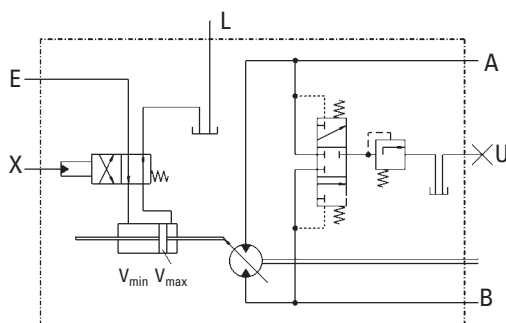
HMV Two Position Features

Two Position	Features		
External Servo Pressure Supply	Minimum Tripping	bar	20
	Maximum Permissible Tripping	bar	40
Hydraulic Control	Shifting Pressure Minimum Tripping	bar	20
	Shifting Pressure Maximum Permissible Tripping	bar	40
Electric Control	Connector Type	Hirschmann, AMP Junior Timer, 2-pin	
	Rated Voltage = Max. Continuous Voltage	V	12 24
	Voltage Type	Dc Voltage	
	Power Input (Old)	W	≤ 26
	Relative Duty Cycle	%	100
	Protection Class	IP 6K6K, part 9	
Minimum Response Time with Standard Orifice With 20 Bar Servo Pressure		s	0.5

Two Position Motor

With Hydraulic Control Pressure and External Servo Supply Pressure

- A,B Work port connections
- L,U Case drain / vent connections
- E Servo supply pressure connection
- X Control connection



Motor Types – HMV

EH1P Stepless with Pressure Override

Stepless Variable Control with Pressure Override Features

Stepless Variable Control with Pressure Override

Features	
Hydraulic control signal	Control pressure range bar 8 to 14
	Maximum permissible pressure bar 40
Hydraulic pressure override	Regulation begin pressure adjustable, please specify with order bar 190-260
	Regulation end pressure bar 5 % above regulation begin pressure
Electric control signal	Connector type Hirschmann, AMP Junior Timer, 2-pin
	Rated voltage = max. continuous voltage 12 24
	Voltage type DC voltage
	Power input (cold) W ≤26
	Relative duty cycle % 100
	Protection class IP 6K6K, part 9
Minimum Response Time with Standard Orifice with 20 bar servo pressure	s 0.5

This motor is used primarily for closed loop operation together with speed-dependent hydraulic pump, type HPV CA. Alternatively, with hydraulically or electro-hydraulically pilot-operated drives for which a high pressure regulating function is also required. Without control signal the motor shifts to maximum displacement V_{max} . Stepless variable control to lower displacement is hydraulic, with control pressure generated by the speed dependent pump. The motor is also equipped with a system pressure override which, at a predefined setting, automatically increases its displacement in response to system related torque demand. The following data are independent of the rated motor size.

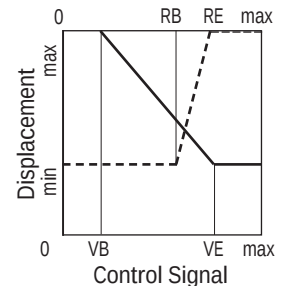
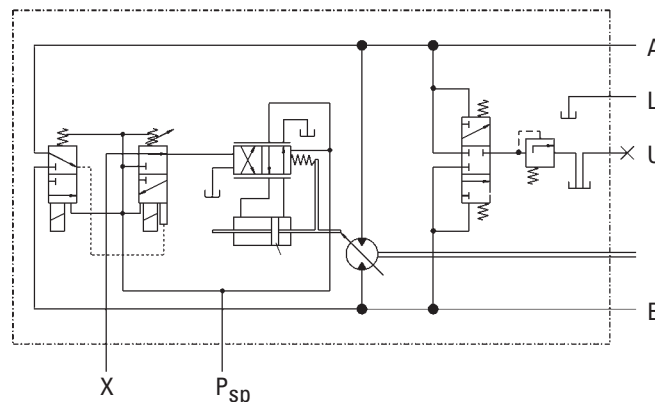
Auxiliary Functions

- Electric V_{max} control, independent of signal pressure, for maximum displacement motor operation
- Electric brake pressure shut off for controlled deceleration

Stepless Variable Displacement Control Motor

With pressure override, electric maximum displacement override and brake pressure shut off

- A,B Work port connections
- L,U Case drain / vent connections
- X Pressure connection for infinitely variable control
- M1 Solenoid for maximum displacement override
- M2 Solenoid for brake pressure shut off
- VB Swash begin
- VE Swash end
- RB Start of pressure override
- RE End of pressure override
- Operating pressure
- Control pressure

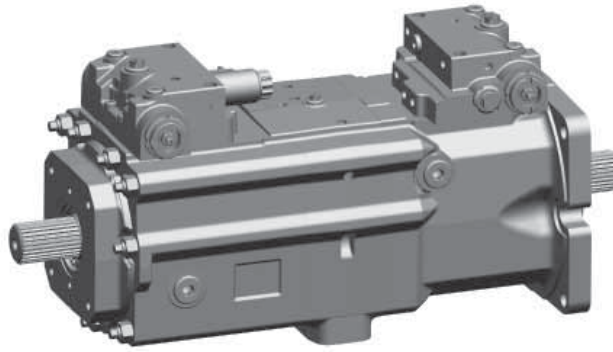


The double motor consists of two Eaton variable motors arranged back-to-back. In addition to a wide torque/speed conversion range it offers the option of direct installation in the drive line, since one or two shaft ends are optionally available for torque output. Noise emission and fuel consumption are reduced because no transfer gearbox is required. At the same time the overall efficiency increases. The performance comparison diagram shows the required drive capacity for different design variants at four operating points.

Motor Types – HMV

D Double Motor

HMV
D Double Motor



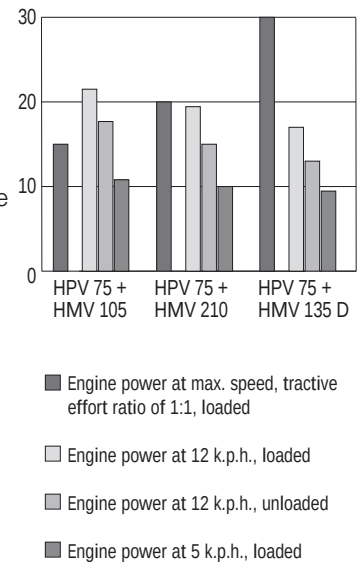
Features

- Two HMV- 02 arranged back-to-back
- Connection for high pressure, servo and control pressure for each motor
- Motor control optionally through 1 signal or 2 separate signals
- Both motors can be set to 0 cm³/rev
- Possible conversion ratio 1:6
- Optionally 2 shaft ends for direct installation in the drive line

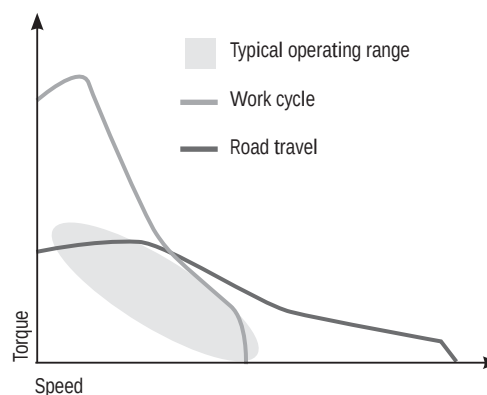
Benefits

- Wide conversion range for stepless acceleration
- Simplified drive line
- High tractive effort and high terminal speed
- Highly dynamic response characteristics
- High starting torque

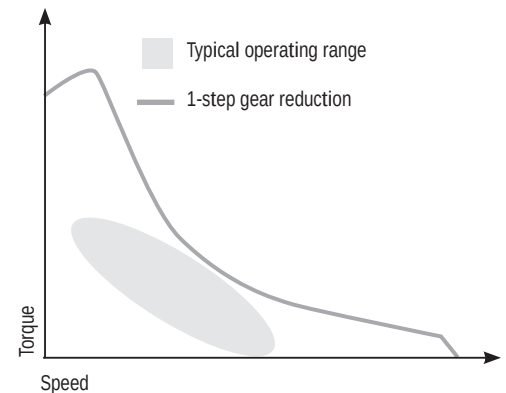
Performance Comparison



2-Position Gearbox with Conventional Transmission



Stepless with Double Motor



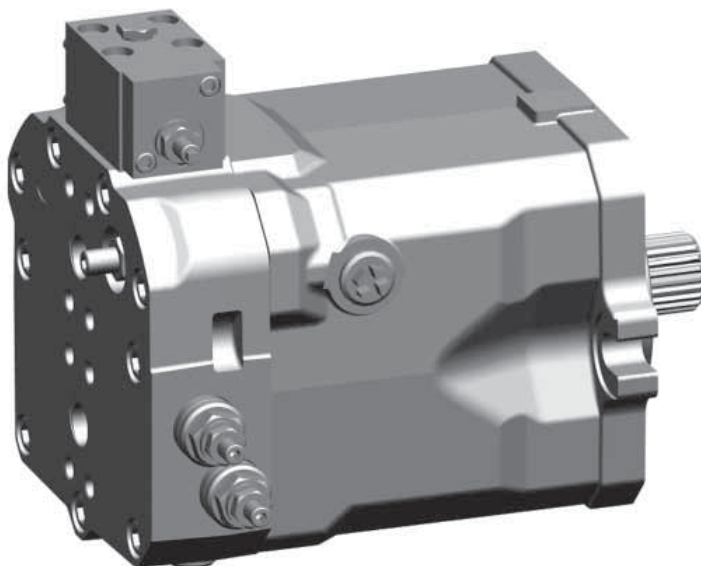
Motor Types – HMR

Regulating Motor

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HMR Regulating Motor



Features

- Optionally with purge valve for circuit and case flushing in closed loop circuit
- System pressure regulation, no external control lines required
- Brake pressure shut off for closed loop circuit
- Counterbalance (brake) valve CBV optional

Benefits

- Smooth low-speed operation
- High starting torque
- Wide conversion range
- Compact design
- High power density
- High reliability
- Long service life
- Highly dynamic response characteristics
- Simplified drive line

Eaton regulating motors are suitable for open and closed loop operation. They are high-pressure regulated and shift to minimum displacement V_{min} at system pressures below the regulation begin point. When the defined high pressure regulation set point is reached, the motor smoothly increases displacement to match the torque required by the system. The following data are independent of the rated motor size.

Motor Types – HMR

Regulating Motor

HMR Features

Typical equipment options

- Open loop circuit.
Secondary (crossline relief) valves or counterbalance (brake) valves
- Closed loop circuit.
Electric brake pressure shut off

Regulating Motor

Features

Hydraulic regulation	Regulation begin pressure	bar	190 to 260
	adjustable, please specify with the order		
	Regulation end pressure	bar	5% above regulation begin pressure
Pneumatic V_{max} override control	Shift pressure min / max	bar	4 to 8
Hydraulic V_{max} override control	Shift pressure min / max Low pressure	bar	20 to 30
	Shift pressure min / max High pressure	bar	30 to 420
Electronic control signal	Connector type		Hirschmann, AMP Junior Timer, 2-pin
Rated voltage = max. continuous voltage		V	12 24
Voltage type			DC Voltage
Power input (cold)		W	≤ 26
Relative duty cycle		%	100
Protection class			IP 6K6K, part 9

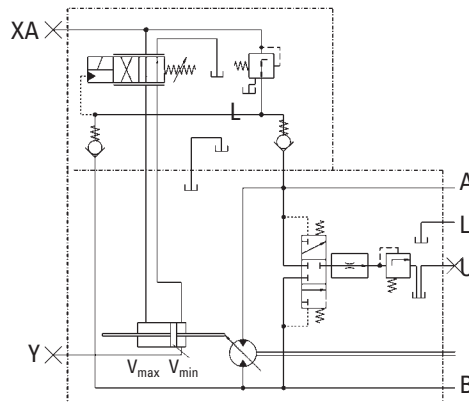
V_{max} Control

The additional V_{max} control enables fixed displacement motor operation independent of the control pressure.

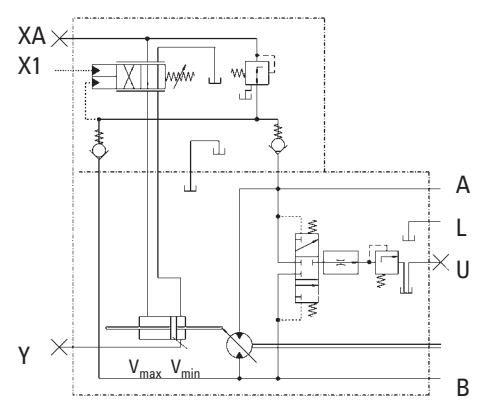
HMR Regulating Motor

- A, B Work port connections
L, U Case drain/vent connections
XA, Y Gauge ports
RB Regulation begin
RE Regulation end
---- Drive torque
— Control pressure

With Electrical V_{max} Override Control



With Hydraulic HP V_{max} Override Control



Motor Types – HMR

Regulating Motor

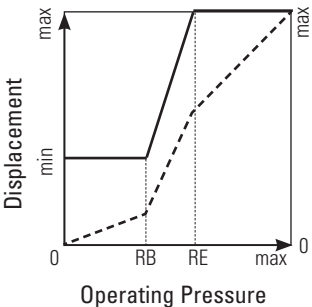
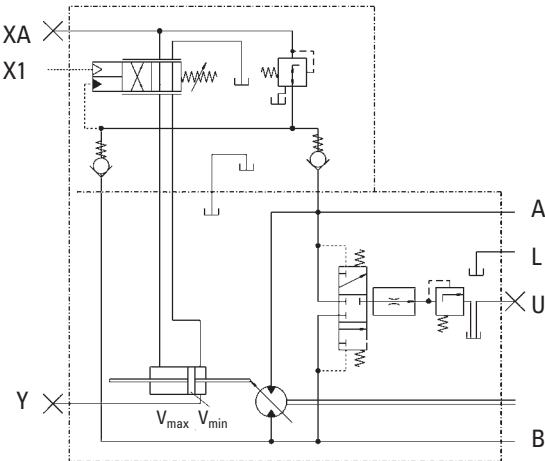
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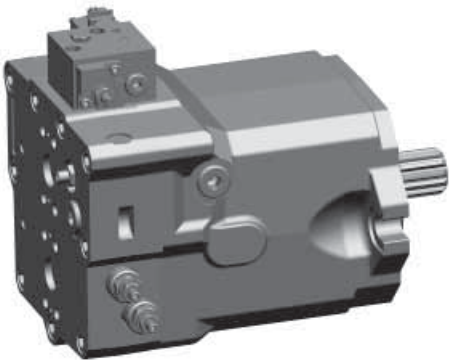
HMR Regulating Motor

With Pneumatic Vmax Override Control

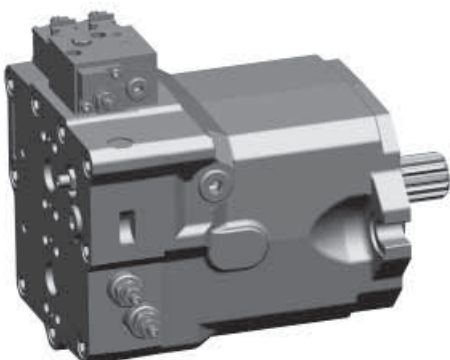
- A, B Work port connections
- L, U Case drain/vent connections
- XA, Y Gauge ports
- RB Regulation begin
- RE Regulation end
- Drive torque
- Control pressure



HMR with Override Electric Maximum Displacement Override



HMR with Electric Maximum Displacement and Brake Pressure Shut Off

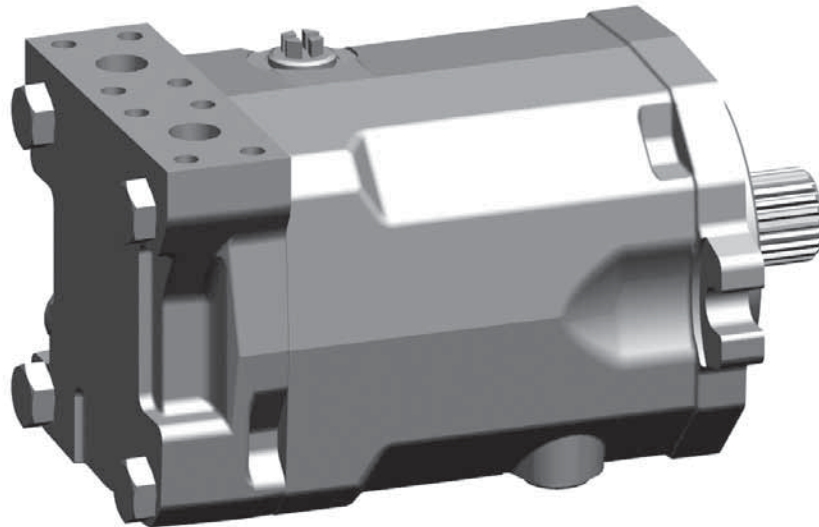


Motor Types – HMF

Fixed Displacement Motor

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Features

- Optimized start-up and low-speed characteristics
- Optionally with purge valves for purge and case flushing
- Fixed and dual setting secondary valves optional

Benefits

- Smooth low-speed operation
- High starting torque
- Compact design
- High power density
- High reliability
- Long service life

Motor Types – HMF

Fixed Displacement Motor

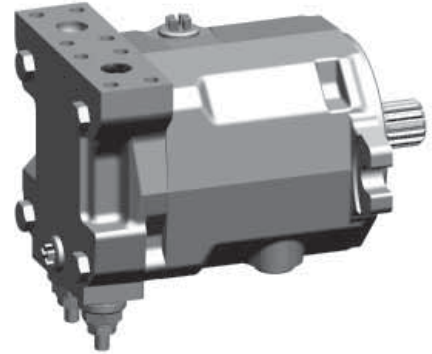
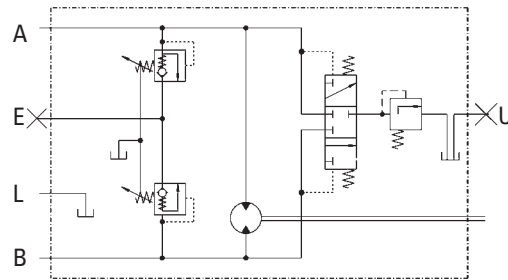
The HMF motor is a high-pressure fixed displacement motor for open and closed loop operation. Secondary valves enable customised definition of soft motor start-up and slowdown. With dual setting secondary valves the maximum acceleration and braking torque is additionally available. The settings and shifting ranges can be adjusted according to project-specific requirements, see section Function. Secondary protection and HMF P.

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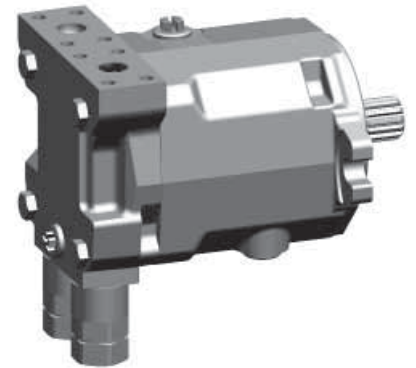
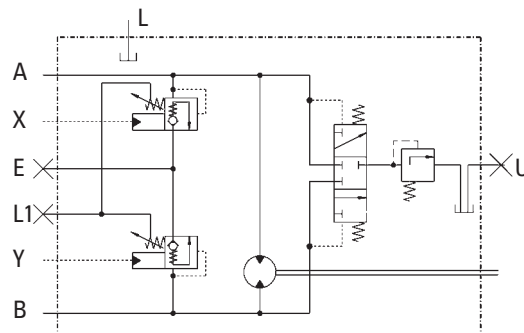
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HMF Fixed Displacement Motor

With Crossline Relief Valves Fixed Setting

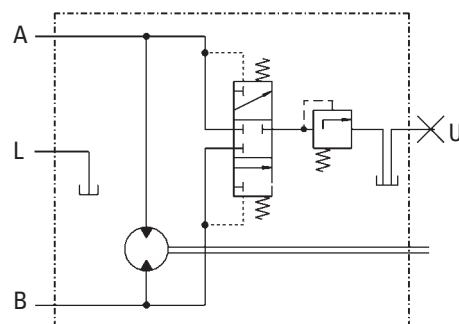


With Dual Pressure Crossline Relief Valves

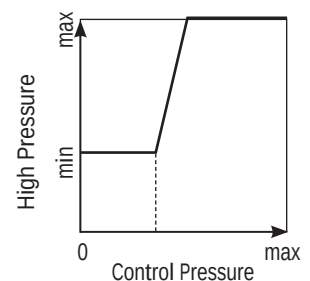


HMF Fixed Displacement Motor

- A, B Work ports
- L, L1, U Case drain/vent connections
- X, Y Control connections for dual pressure crossline relief valve
- E Make up connection



Dual Pressure Relief Valve, Pressure Setting



Motor Types – HMF P

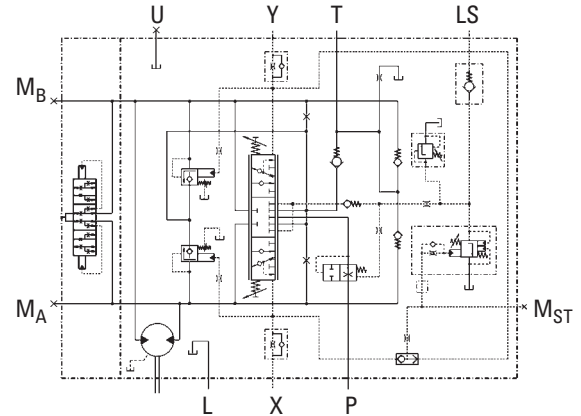
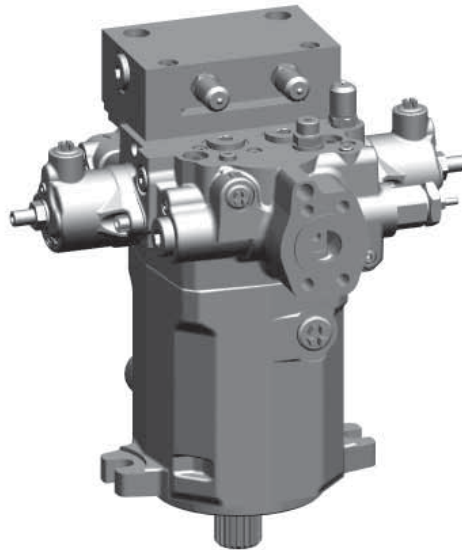
Fixed Displacement Motor

The HMF motor is a high-pressure fixed displacement motor for open loop operation. With integrated LS directional control valve and TC torque control it combines the benefits of the Eaton with all auxiliary functions typically required for application in swing and winch drives.

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HMF P with Integrated Swing Function



P, T Work port connections
L, U Case drain/vent connections
LS LS-pressure connection
M Gauge ports

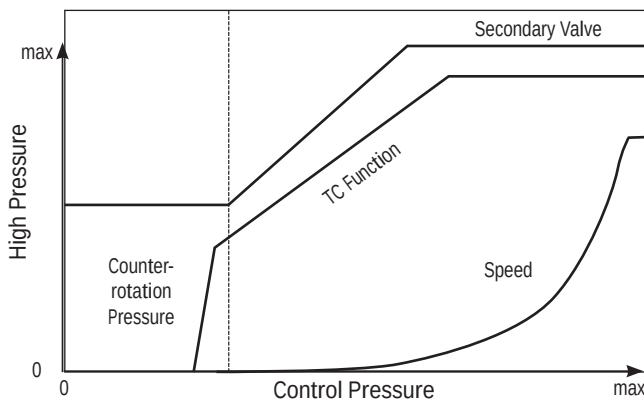
Features

- Directional control valve function
- Torque control function
- HP valves with controllable characteristic curve
- Priority function
- Secondary protection combined with make-up function
- Purge and case flushing function
- Anti-reaction valve

Benefits

- Smooth low-speed operation
- High starting torque
- Torque and speed control
- Controllable counter-rotation
- Compact design
- High power density
- High reliability
- Long service life

TC Function



For powerful and dynamic application in swing drives the TC function enables control pressure-dependent acceleration. Once the maximum rotating speed is reached, torque control is superimposed and pressure level is reduced for energy-saving operation.

If the control valve is reset to the neutral position, no

additional control signal is generated and the rotary motion slows down uniformly. Active counter-rotation is possible with controllable secondary valves. A counteractive control signal is generated, and the rotary motion is decelerated along the characteristic counter-rotation pressure curve.

Motor Types – HMA

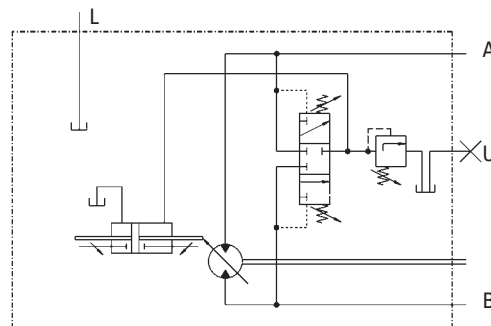
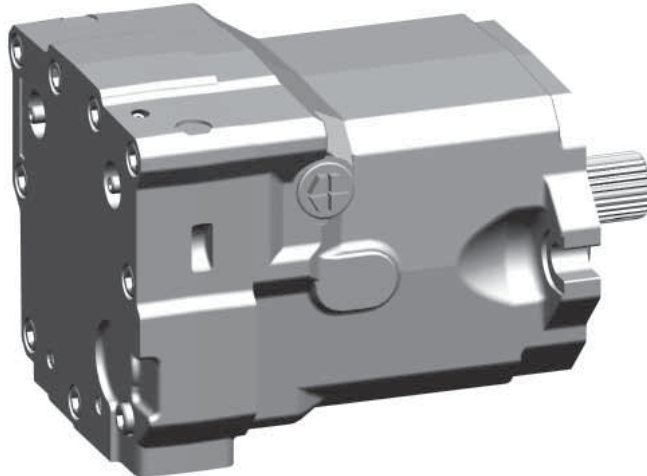
Adjustable - Fixed Displacement Motor

The HMA motor is a high-pressure motor with adjustable displacement for open and closed loop operation. For application which requires dependent on the situation a reduced or increased displacement, the HMA offers the expected flexibility. Since the displacement can be adjusted on request stepless at a screw. For a well-adjusted torque.

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HMA Adjustable - Fixed Displacement Motor



A, B Work port connections
L, U Case drain / vent connections

Rated Size	55	75	105	135	165	210	280
Flange Profile	2-hole Mounting Flange			4-hole		4-hole	
	SAE C	SAE C	SAE C	SAE D	SAE D	SAE E	SAE E
Shaft Profile in accordance with ANSI B92.1	21 teeth	21 teeth	16/32 spline pitch 23 teeth	23 teeth	23 teeth	8/16DP 15 teeth	15 teeth
D1 (mm)	127	127	127	152.4	152.4	165.1	165.1
B1 (mm)	181	181	181	228.6	228.6	224.5	224.5
B2 (mm)	208	208	208	258.0	258.0	269.0	269.0
B3 (mm)	86	95	96	108.0	125.0	134.0	156.0
B4 (mm)	95	95	96	108.0	125.0	134.0	156.0
B5 (mm)	86	95	96	108.0	125.0	on demand	on demand
B6 (mm)	85	95	96	108.0	125.0	on demand	on demand
B7 (mm) with electric override control	—	180	181	193	on demand	on demand	on demand
B8 (mm) with electric override control	—	180	181	193	on demand	on demand	on demand
H1 (mm)	80	86	91	98	98	135.0	135.0
H2 (mm)	83	93	99	103	98	135.0	135.0
H3 (mm)	84	93	95	108	120	134.0	151.5
H4 (mm)	90	105	106	114	132	133.0	152.5
H5 (mm)	84	93	96	107	118	on demand	on demand
H6 (mm)	90	105	105	114	132	on demand	on demand
H7 (mm) with electric override control	—	88	88	88	on demand	on demand	on demand
H8 (mm) with electric override control	—	92	92	92	on demand	on demand	on demand
L1 (mm)	41	56	56	75	75	75	75
L2 (mm)	212	226	247	270	314	336	381
L3 (mm) control	hydraulic control electric control	33 75	33 75	33 75	5 58	5 55	8 59
L4 (mm)	217	231	252	275	305	on demand	on demand
L5 (mm) control	hydraulic control electric control	18 70	18 70	18 70	5 58	on demand on demand	on demand on demand
L6 (mm) with electric override control	—	33	33	33	on demand	on demand	on demand
L7 (mm) with electric override control	—	28	28	28	on demand	on demand	on demand
L8 (mm) with electric override control	—	80	80	80	on demand	on demand	on demand
L, U	M22x1.5	M22x1.5	M22x1.5	M22x1.5	M27x2	M27x2	M33x2
E				M14x1.5			
Connection for external servo supply pressure feed							
X				M14x1.5			
Connection for hydraulic control							
M, M1				see section Motor Types. HMV stepless			
Solenoid for electric control							
M2				see section Motor types. HMV stepless			
Solenoid for brake pressure shut off							

Metric connection thread according to ISO 6149

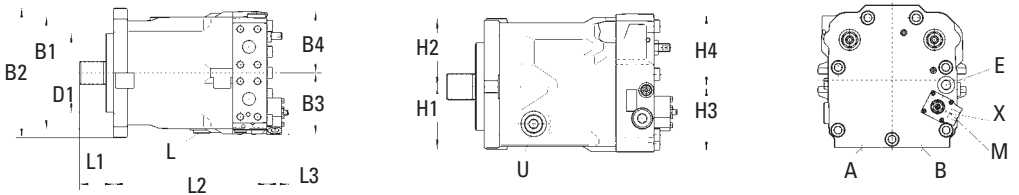
Locking thread for the SAE high pressure-connections, metric according to ISO 261

Hexagon socket head cap screws according to ISO 4762

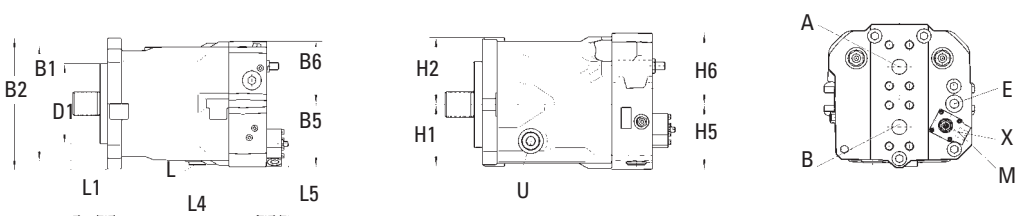
Further threads, dimensions and versions with speed sensor are available on request

HMV

Radial High Pressure-Connections



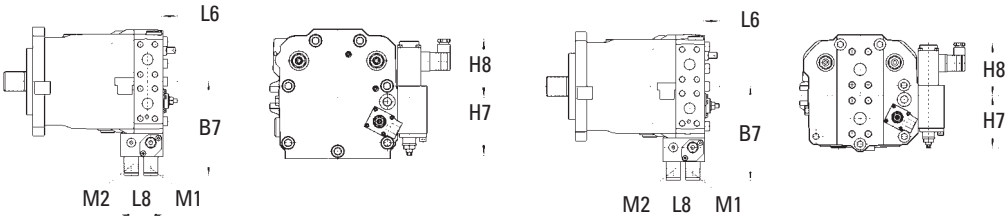
Axial High Pressure-Connections



HMV
with Electric Override
Control

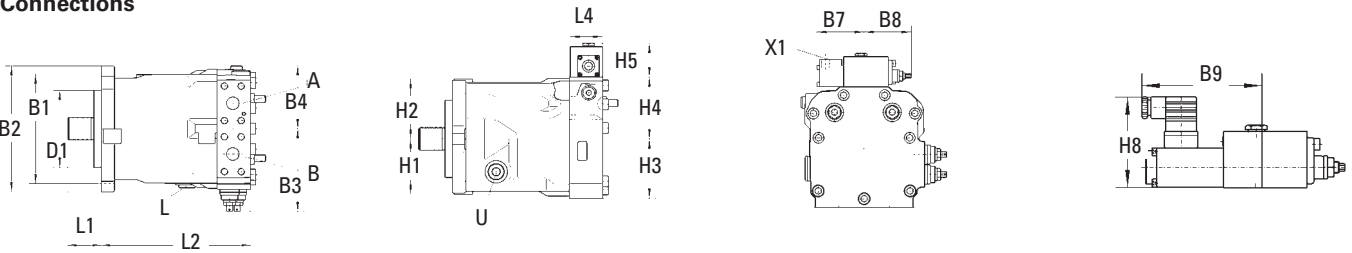
Radial High Pressure-Connections

Axial High Pressure-Connections

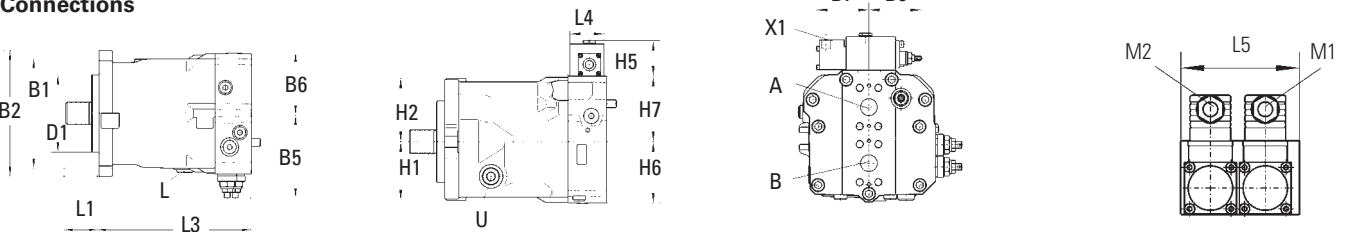


HMR

Radial High Pressure-Connections



Axial High Pressure-Connections



Dimensions – HMR

With Brake Valve – High Pressure-Connections

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Rated Size		75	105	135	165
Flange Profile		SAE C	2-hole mounting Flange		
			SAE C	SAE D	SAE D
Shaft Profile			16/32 spline pitch		
in accordance with ANSI B92.1		21 teeth	21 teeth	23 teeth	23 teeth
D1 (mm)		127	127	152.4	152,4
B1 (mm)		181	181	228,6	228,6
B2 (mm)		208	208	256	256
B3 (mm) sec. relief valve	without	95	99	108	—
	with	135	136	140	—
B4 (mm) sec. relief valve	without	95	105	108	—
	with	12	105	114	—
B5 (mm) sec. relief valve	without	95	99	108	108
	with	135	139	141	148
B6 (mm)		102	105	114	125
B7 (mm)	pneumatic hydraulic	74	74	74	—
		62	62	46	46
B8 (mm)		78	78	78	78
B9 (mm)		103	103	103	103
B10 (mm)		89	89	169	169
B11 (mm)		130	130	107	107
H1 (mm)		86	91	96	98
H2 (mm)		93	99	100	105
H3 (mm)		93	98	108	—
H4 (mm)		102	102	110	—
H5 (mm)		56	56	56	56
H6 (mm)		91	96	107	118
H7 (mm)		102	107	109	125
H8 (mm)		81	81	81	81
H9 (mm)		85	85	102	102
L1 (mm)		56	56	75	75
L2 (mm)		229	247	270	—
L3 (mm)		231	252	275	304
L4 (mm)		53	53	53	53
L5 (mm)		80	80	80	80
regulator with el. maximum displacement override and brake pressure shuf off					
L6 (mm)		127	127	120	120
L, U		M22x1.5	M22x1.5	M27x2	M27x2
X1					
port for hyd. / pneum. max. displ. override			M14x1.5		
M1			see section Motor Types. HMR		
solenoid for electric maximum displacement override					
M2			see section Motor Types. HMR		
solenoid for brake pressure shut off					

Metric connection thread according to ISO 6149

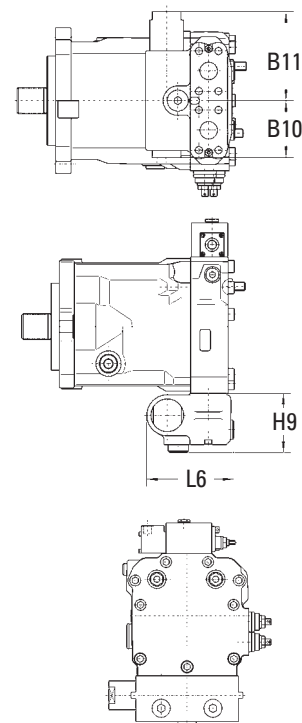
Locking thread for the SAE high pressure-connections, metric according to ISO 261

Hexagon socket head cap screws according to ISO 4762

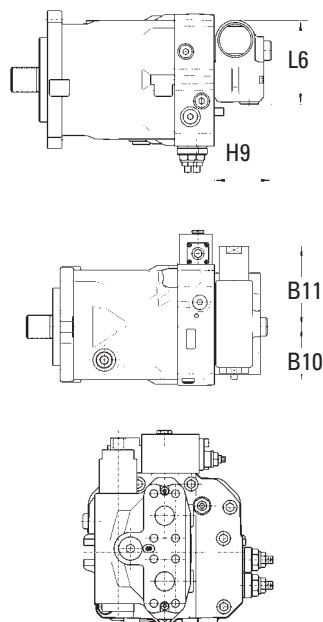
Further threads, dimensions and versions with speed sensor are available on request

HMR with Brake Valve

Radial High Pressure-Connections



Axial High Pressure-Connections



Dimensions – HMF

High Pressure-Connections

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Rated Size	28	35	50	75	105	135	165 HMA	210 HMA
Flange Profile	2-hole Mounting Flange				4-hole			
	SAE B	SAE B	SAE C	SAE C	SAE C	SAE D	SAE D	SAE E
Shaft Profile			16/32 spline pitch					8/16DP
in accordance with ANSI B92.1	15 teeth	15 teeth	21 teeth	21 teeth	23 teeth	23 teeth	23 teeth	15 teeth
D1 (mm)	101.6	101.6	127	127	127	152.4	152.4	165.1
B1 (mm)	146	146	181	181	181	228.6	228.6	224.5
B2 (mm)	162	162	200	200	200	250	258	269
B3 (mm)	146	146	146	166	166	166	250	268
B4 (mm)	149	149	149	169	169	169	250	268
H1 (mm)	61	61	70	73	82	86	98	135
H2 (mm)	61	61	70	73	82	86	98	135
H3 (mm)	67	67	72	78	83	89	120	134
Crossover relief valves	without	67	72	78	83	89	120	134
	with fixed setting	108	108	119	128	137	—	—
	with dual pressure setting	129	129	140	149	158	—	—
H4 (mm)	69	69	69	79	83	88	132	133
H5 (mm)	64	64	69	75	80	86	132	133
L1 (mm)	41	41	56	56	56	75	75	75
L2 (mm)	193	193	202	229	254	277	314	336
L3 (mm)	191	191	200	227	252	275	305	336
L, U	M22x1.5						M27X2	M27X2
E	M18x1.5			M22x1.5			—	—

Connection for anti-cavitation oil supply

Metric connection thread according to ISO 6149

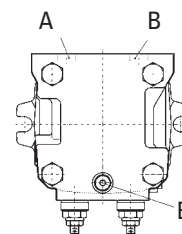
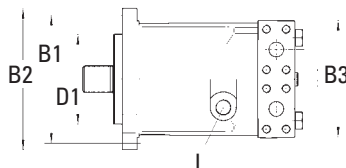
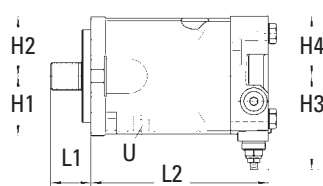
Locking thread for the SAE high pressure-connections. Metric according to ISO 261

Hexagon socket head cap screws according to ISO 4762

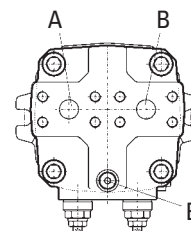
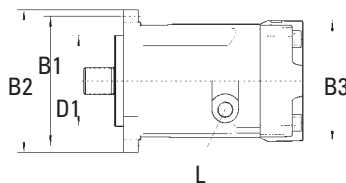
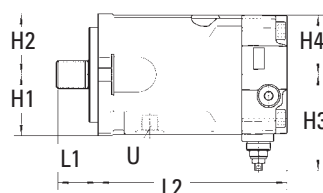
Further threads are available on request

HMF High Pressure-Connections

Radial High Pressure-Connections



Axial High Pressure-Connections



Dimensions – Plug-in Motors and Connections

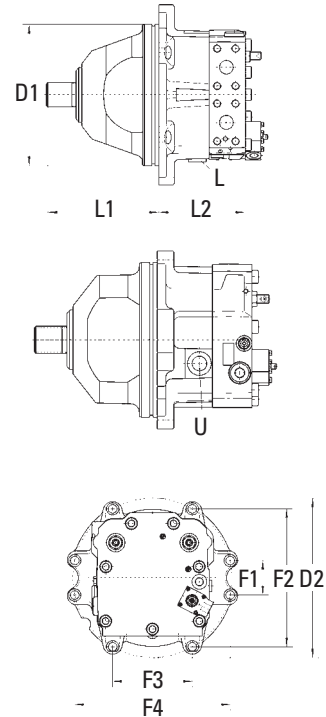
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Plug-in Motors

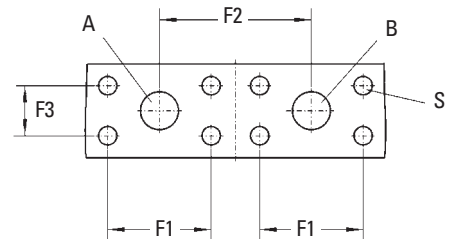
Here variable motor as example.
For dimensions not listed please
see tables before.

Rated Sizes	75	105	135
D1 (mm)	190.0	216.0	216.0
D2 (mm)	251.0	282.0	282.0
F1 (mm) 2-hole flange	—	55.8	55.8
F2 (mm) 2-hole flange	0.0	223.4	223.4
F3 (mm) 2-hole flange	—	129.0	129.0
F4 (mm) 2-hole flange	224.0	251.8	251.8
L1 (mm)	143.0	169.0	169.0
L2 (mm)	124.0	132.0	175.0



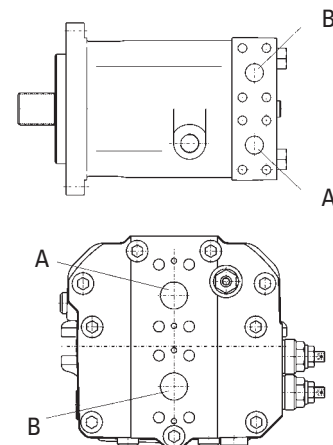
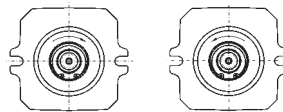
Dimensions – Connections

Rated Size	28/35	50/55	75	105	135	165	210	280	135D
F1 (mm)	50.8	50.8	57.2	57.2	57.2	66.6	66.6	66.6	57.2
F2 (mm)	74.0	74.0	84.0	84.0	84.0	102.0	102.0	102.0	84.0
F3 (mm)	23.8	23.8	27.8	27.8	27.8	31.8	31.8	31.8	27.8
A, B (mm)	¾"	¾"	1"	1"	1"	1 ¼"	1 ¼"	1 ¼"	1"
S (mm)	M10	M10	M12	M12	M12	M14	M14	M14	M12



Input Flow and Drive Shaft Rotation

High Pressure at Port	Shaft Output Direction of Rotation	Right Hand	Left Hand
	HMV	B	A
	HMR	B	A
	HMF	A	B



Modular System Features

The Eaton motors are based on a modular system with the following characteristics. This enables our distribution partners to configure the product according to your requirements. The modular system is expanded continuously. Please consult our sales department for the latest characteristics.

Modular System

Features

- $V_{\min}$
- Mounting flange
- Drive shaft
- $V_{\max}$ control
- Control orifice
- Secondary valves
- Direction of HP-connections
- Purge valve setting
- Shuttle valve
- Drain port U, L1, L2
- Coupling flange
- PTO through-Drive
- Port threads
- Type of control
- Remote control pressure
- Start of control
- Voltage for E-controls
- Connectors for E-controls
- Displacement fixing
- Speed sensor
- Pilot pressure compensation
- Surface treatment

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Powering Business Worldwide

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Printed in USA
Document No. E-MOPI-MC003-E1
Supersedes E-MOPI-MC003-E
September 2010